NPFL108 – Bayesian inference

Approximate Inference

Laplace approximation

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Outline

- Laplace approximation
- Probit regression model

The Laplace Approximation

• The simplest deterministic method for approximate inference

Restricted to models in which the variables of interest are continuous

 The factors for the continuous random variables will generally be some continuous parametric functions

The Laplace Approximation: Univariate case 1

- The Laplace approximation will find a Gaussian approximation to the conditional distribution of a set of continuous variables
- We are interested in approximating posteriors
- Consider a single scalar variable w:

$$p(w|D) = \frac{1}{Z}p(w,D) = \frac{1}{Z}p(D|w)p(w) = \frac{1}{Z}f(w)$$

- D are observed variables, therefore fixed and can be omitted
- Z is a normalisation constant

$$Z = \int p(w, D) dw = \int f(w) dw$$

• We want to find w_0 and A such that

$$p(w|D) \approx N(w; w_0, A^{-1})$$

The Laplace Approximation: Univariate case 2

• First, find a mode (i.e. local maximum w₀) of p(w|D)

$$\frac{df(w)}{dw} = 0$$

=> w₀

- Any algorithm can be used
 - including numerical solution
- We do not work with p(w|D) because we do not know Z!
 - We do not need it to find maximum!
- Instead we work with f(w) which is typically easily available.

f(w) =likelihood × prior

The Laplace Approximation: Univariate case 3

 Second, compute a truncated Taylor expansion of log f(w) centre at the mode

-1

$$\log f(w) \approx \log f(w_0) + \frac{1}{2}A(w - w_0)^2$$

$$A = -\frac{d^2}{dw^2} \log f(w); w = w_0$$

• Taking the exponential:

where

 \bullet

$$f(w) \approx f(w_0) \exp\left\{\frac{1}{2}A(w-w_0)^2\right\}$$

$$\frac{1}{\sqrt{2\pi A^{-1}}}$$
variance mean

• One can see that this looks like a normal distribution

$$p(w|D) \approx N(w; w_0, A^{-1}) = \frac{1}{\sqrt{2\pi A^{-1}}} \exp\left\{\frac{(w - w_0)^2}{2A^{-1}}\right\}$$

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The Laplace Approximation: Multi-variate Case

- The same principle can be applied to approximate an
 - M-dimensional distribution

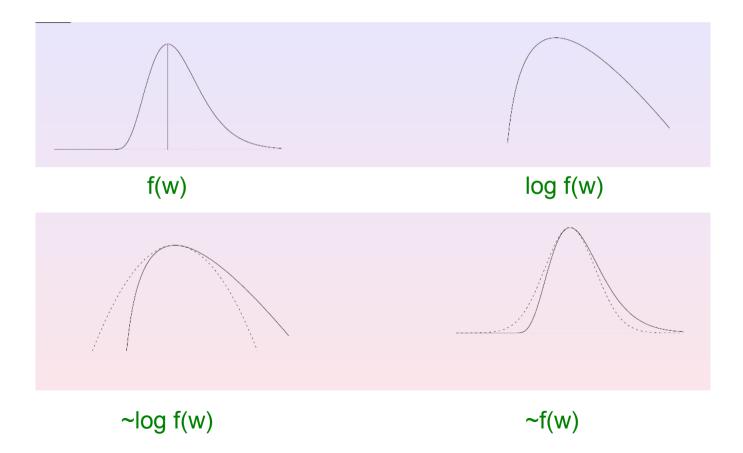
$$\log f(\mathbf{w}) \approx \log f(\mathbf{w}_0) + \frac{1}{2} (\mathbf{w} - \mathbf{w}_0)^T \mathbf{A} (\mathbf{w} - \mathbf{w}_0)$$
$$\mathbf{A} = -\nabla \nabla \log f(\mathbf{w}); \mathbf{w} = \mathbf{w}_0$$
$$f(\mathbf{w}) \approx f(\mathbf{w}_0) \exp\left\{\frac{1}{2} (\mathbf{w} - \mathbf{w}_0)^T \mathbf{A} (\mathbf{w} - \mathbf{w}_0)\right\}$$

• The approximation has mean of \mathbf{w}_0 and covariance matrix \mathbf{A}^{-1}

$$p(\mathbf{w}|D) \approx N(\mathbf{w};\mathbf{w}_0,\mathbf{A}^{-1})$$

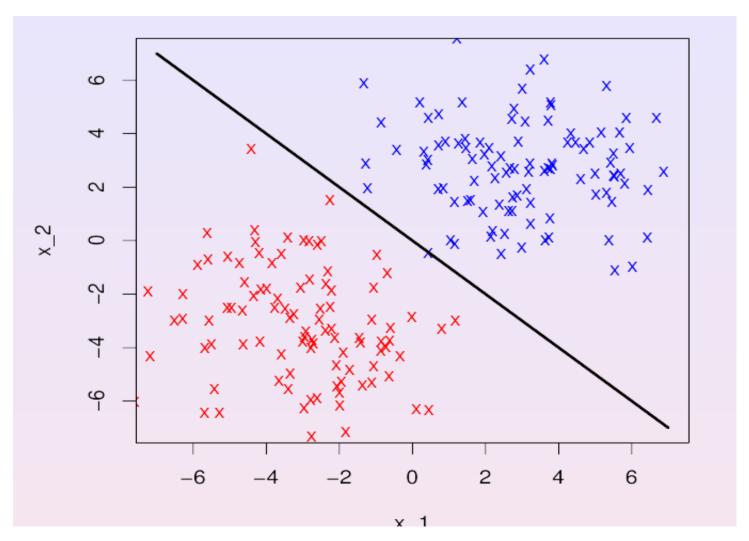
The Laplace Approximation: example

 The Gaussian approximation will only be defined if A is positive semidefinite, i.e., w₀ must be a local maximum not a minimum or a saddle point.

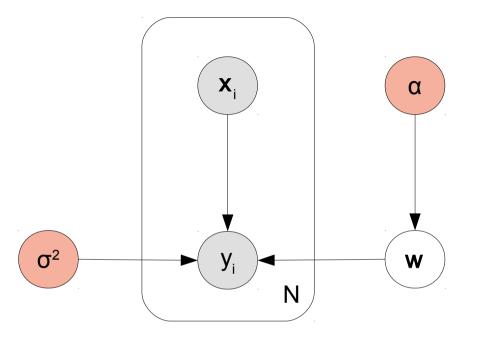


Probit regression model

- Similar to logistic regression
- Useful for binary classification



Probit regression: graphical model



$$y_{i} = \begin{cases} 1 & \text{if } \mathbf{w}^{T} \mathbf{x}_{i} + \epsilon_{i} \geq 0 \\ -1 & \text{if } \mathbf{w}^{T} \mathbf{x}_{i} + \epsilon_{i} < 0 \end{cases}$$
$$\mathbf{w} \sim N(\mathbf{0}, \mathbf{I}\alpha)$$
$$\epsilon_{i} \sim N(0, \sigma^{2})$$

$$p(y_i | \mathbf{x}_i; \mathbf{w}) = \Phi(y_i \mathbf{w}^t \mathbf{x}_i; 0, \sigma^2)$$

- w are our parameters
- y_i,x_i are our observations data D

$$p(\mathbf{y}, \mathbf{w} | \mathbf{x}) = p(\mathbf{y} | \mathbf{x}; \mathbf{w}) p(\mathbf{w})$$
$$p(\mathbf{y} | \mathbf{x}; \mathbf{w}) p(\mathbf{w}) = \prod_{i=1}^{N} p(y_i | \mathbf{x}_i; \mathbf{w}) p(\mathbf{w}) = \prod_{i=1}^{N} \Phi(y_i \mathbf{w}^t \mathbf{x}_i; 0, \sigma^2) N(\mathbf{w}; \mathbf{0}, \mathbf{I}\alpha)$$

Probit regression model

• For the sake of completeness, probit function

$$\Phi(a;\mu,\sigma^2) = \int_{-\infty}^a N(a;\mu,\sigma^2) da$$

We want to make inference of w given some observed labels
 y and x

$$p(\mathbf{w}|\mathbf{y}, \mathbf{x}; \alpha, \sigma^2) = \frac{p(\mathbf{y}|\mathbf{x}, \mathbf{w}; \sigma^2)p(\mathbf{w}; \alpha)}{p(\mathbf{y}|\mathbf{x})}$$

- For simplicity, we consider that $\sigma^2 = 1$ and that $\alpha = 1$.
- The posterior distribution is:

 $p(\mathbf{w}|\mathbf{y}, \mathbf{x}) \propto p(\mathbf{y}|\mathbf{x}; \mathbf{w})p(\mathbf{w})$

Recall 1

$$p(\mathbf{y}|\mathbf{x};\mathbf{w})p(\mathbf{w}) = \prod_{i=1}^{N} p(y_i|\mathbf{x}_i;\mathbf{w})p(\mathbf{w}) = \prod_{i=1}^{N} \Phi(y_i\mathbf{w}^t\mathbf{x}_i;0,1)N(\mathbf{w};\mathbf{0},\mathbf{I})$$

Recall 2

$$f(\mathbf{w}) = p(\mathbf{y}|\mathbf{x}; \mathbf{w})p(\mathbf{w})$$
$$f(\mathbf{w}) = \prod_{i=1}^{N} \Phi(y_i \mathbf{w}^t \mathbf{x}_i; 0, 1)N(\mathbf{w}; \mathbf{0}, \mathbf{I})$$

- Using some numerical optimisation algorithm
 - find \mathbf{w}_0 a local maximum of

$$f(\mathbf{w}) = \prod_{i=1}^{N} \Phi(y_i \mathbf{w}^t \mathbf{x}_i; 0, 1) N(\mathbf{w}; \mathbf{0}, \mathbf{I})$$

• Perform Taylor expansion of

$$\log f(\mathbf{w}) = \log p(\mathbf{y}|\mathbf{x};\mathbf{w}) + \log p(\mathbf{w})$$
$$\log f(\mathbf{w}) = \sum_{i=1}^{N} \log \Phi(y_i \mathbf{w}^t \mathbf{x}_i; 0, 1) - \frac{1}{2} \mathbf{w}^T \mathbf{w} - \frac{1}{2} \log 2\pi$$

- Let \mathbf{w}_0 be a maximum of $f(\mathbf{w})$
- Computing the negative Hessian at w₀ of log f(w)

$$\mathbf{A} = -\nabla\nabla\log f(\mathbf{w}) = \sum_{i=1}^{N} [v_i(y_i \mathbf{w}_0^T \mathbf{x}_i + v_i)\mathbf{x}_i \mathbf{x}_i^T] + \mathbf{I}$$
$$v_i = \frac{N(y_i \mathbf{w}_0^T \mathbf{x}_i; 0, 1)}{\Phi(y_i \mathbf{w}_0^T \mathbf{x}_i)}$$

- Approximation of $p(\mathbf{w}|\mathbf{y},\mathbf{x})$ is

$$p(\mathbf{w};\mathbf{w}_0,\mathbf{A}^{-1}) = N(\mathbf{w};\mathbf{w}_0,\mathbf{A}^{-1})$$

Predictive distribution

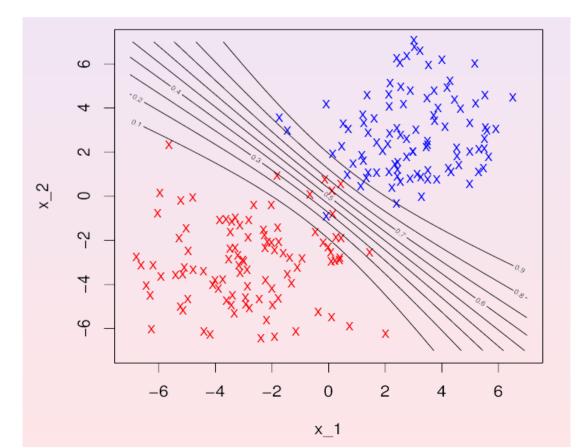
• We also want to compute a predictive distribution for new unlabelled instances

$$p(y_{new}|\mathbf{x}_{new}, \mathbf{y}, \mathbf{x}, \alpha, \sigma^2) = \int p(y_{new}|\mathbf{x}_{new}, \mathbf{w}) p(\mathbf{w}|\mathbf{y}, \mathbf{x}, \alpha, \sigma^2) d\mathbf{w}$$

- Thanks to probit model and the Laplace Approximation
 - It is possible to compute an approximate predictive distribution

$$p(y_{new}|\mathbf{x}_{new}, \mathbf{y}, \mathbf{x}, \alpha, \sigma^2) = \int p(y_{new}|\mathbf{x}_{new}, \mathbf{w}) N(\mathbf{w}|\mathbf{w}_0, \mathbf{A}^{-1}) d\mathbf{w}$$
$$= \int \Phi(y_{new}\mathbf{w}^T\mathbf{x}_{new}) N(\mathbf{w}|\mathbf{w}_0, \mathbf{A}^{-1}) d\mathbf{w}$$
Hurray! We know how to compute the integral.
$$\Phi\left(\frac{y_{new}\mathbf{w}^T\mathbf{x}_{new}}{\sqrt{\mathbf{x}_{new}^T + \mathbf{A}^{-1}\mathbf{x}_{new} + 1}}\right)$$

- Uncertainty is high near the decision boundary and progressively decreases as we move away from it.
- Uncertainty is significantly larger in regions where there is no data.



The Laplace Approximation: Considerations

- The mode of log f can be found using a numerical optimization method.
- The Hessian can be approximated by differences.
- Many distributions can be multi-modal, what leads to many different Laplace approximations, depending on the mode.
- In many cases, the posterior distribution of z will converge to a Gaussian as the number of observations (evidence) increases.
- Only applicable on real variables.
- Only focuses around the mode and can fail to capture global properties.
- No need to know Z.

Thank you!

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