

# NPFL099 - Statistical dialogue systems

Dialogue management

## Belief monitoring I

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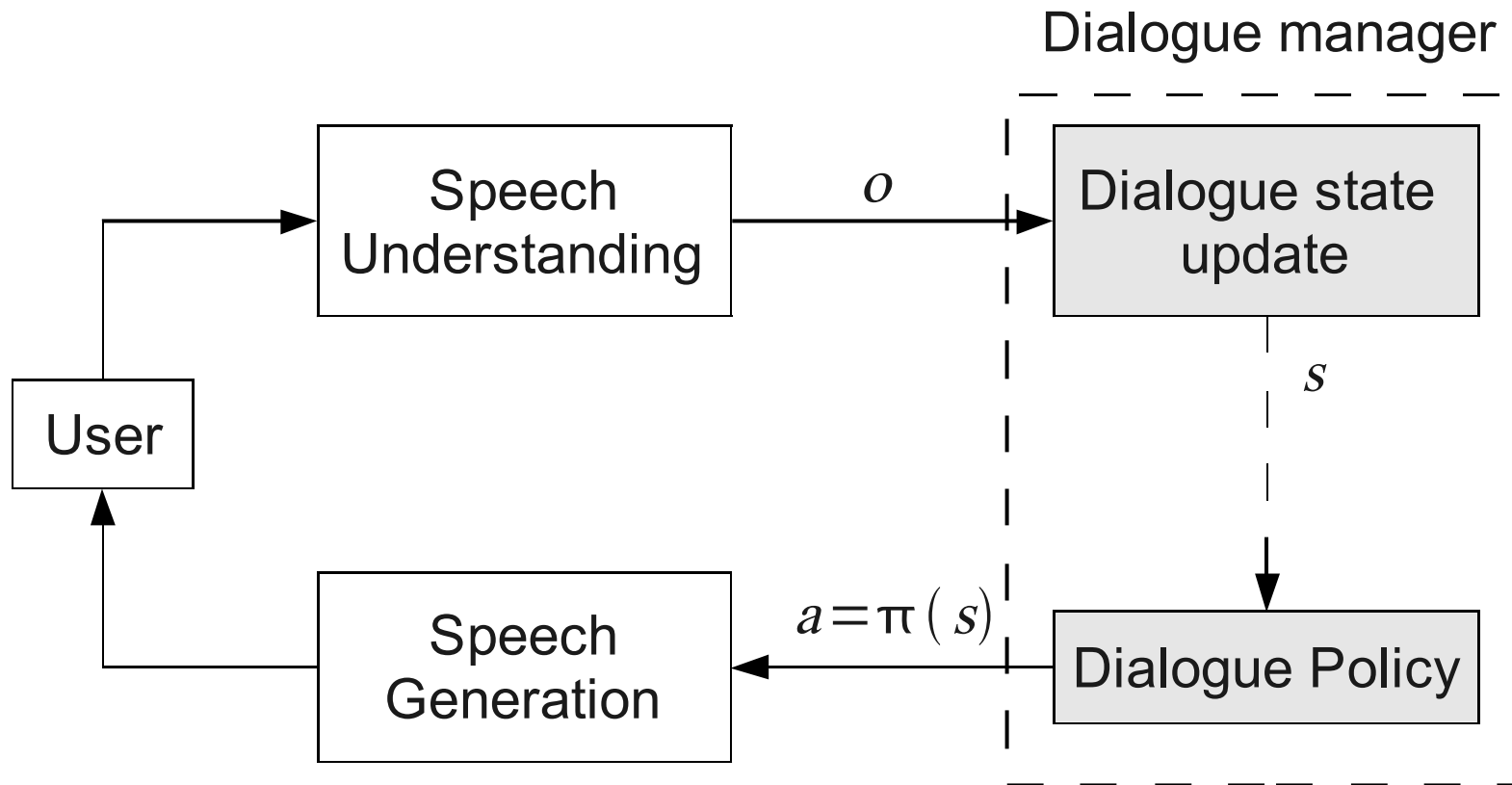
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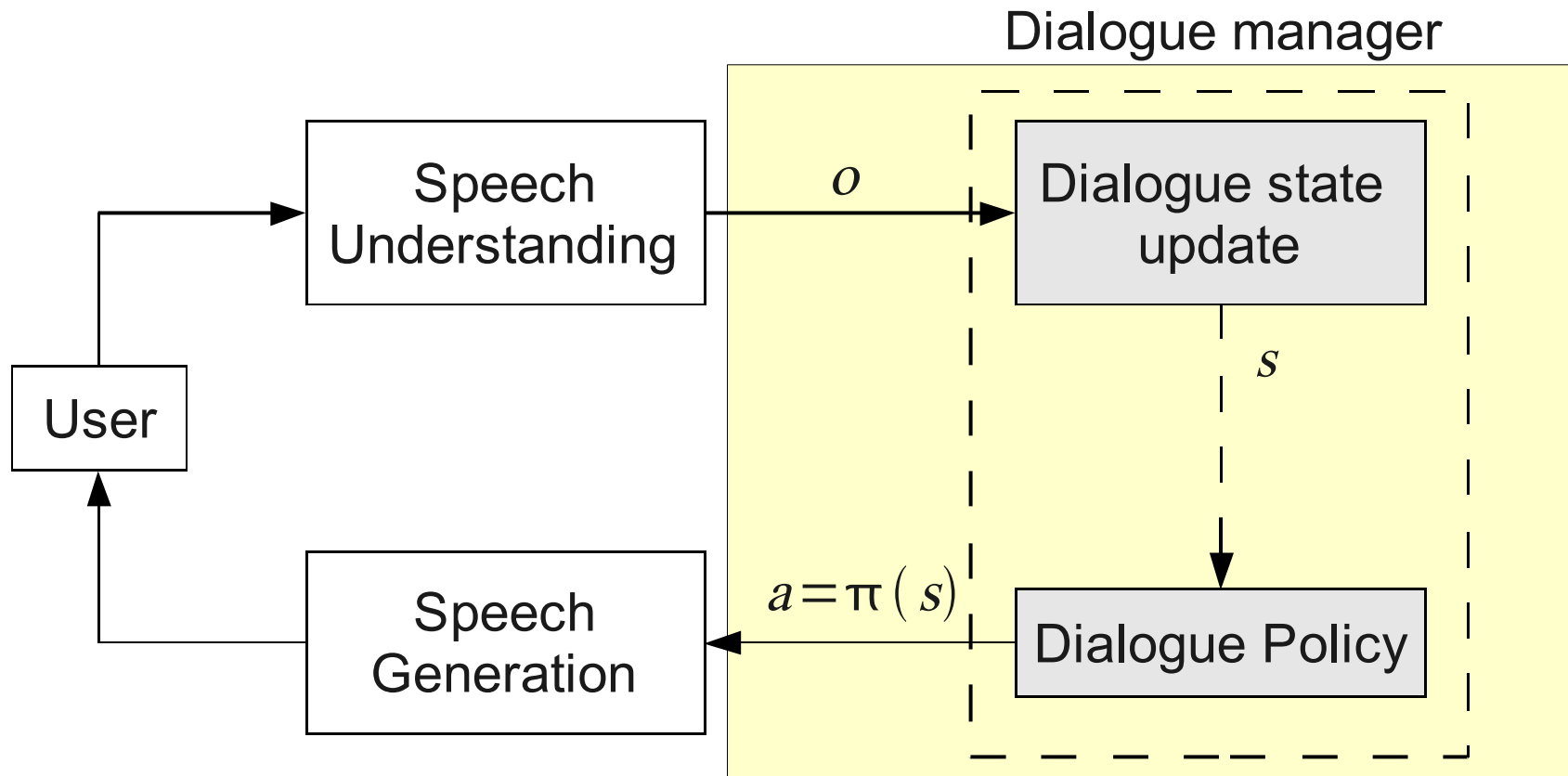
# Outline

- What is a dialogue manager?
- Dialogue state definition
- Motivation for statistical SDS
- Dialogue state estimation
- State enumeration and pruning

# Typical spoken dialogue systems



# Dialogue state and policy



- Dialogue state is composed of **variables** needed to track the the progress of the dialogue
- Policy is implemented as a sequence of **if/then decision**

# Example: TownInfo application

- Queries about
  - restaurants, bars, and hotels
- Search constraints
  - area, price range, stars
- Provides
  - address, postcode, phone number
- BUDS by B. Thomson, CAM, UK
  - Call (22191) 9888
- ALEX by DSG, UFAL, CZ ;-)
  - Call (22191) 9889

# Example of conversation

| Turn   | Transcription                      | Dialogue act                  |
|--------|------------------------------------|-------------------------------|
| System | Hello. How may I help you?         | hello()                       |
| User   | Hi, I am looking for a restaurant. | inform(venue_type=restaurant) |
| System | What type of food would you like?  | request(food_type)            |
| User   | I want Italian.                    | inform(food_type=Italian)     |
| System | Did you say Italian                | confirm(food_type=Italian)    |

## Real user input

|        |  |  |
|--------|--|--|
| User   | 0.4 hi I am looking for a restaurant<br>0.2 uhm am looking for a bar | 0.7<br>inform(venue_type=restaurant)<br>0.3 inform(venue_type=bar) |
| System | Did you say that you are looking for a restaurant?                   | confirm(venue_type=restaurant)                                     |

# Dialogue state

Dialogue state is used to track the progress of the dialogue

E.g. a set of random variables:

- venue\_type
- food\_type
- price\_range
- area
- stars

# User says

Dialogue state is used to track the progress of the dialogue

- Turn 1:
  - S: How may I help you?
- Dialogue state:
  - venue\_type = None
  - food\_type = None
  - price\_range = None
- U: inform(venue\_type = restaurant)



# Dialogue state update

Dialogue state is used to track the progress of the dialogue

- Turn 1:
  - S: How may I help you?
  - Dialogue state:
    - **venue\_type = restaurant**
    - food\_type = None
    - price\_range = None
  - **U: inform(venue\_type = restaurant)**



Dialogue state update

# System says

Dialogue state is used to track the progress of the dialogue

- Turn 2:
  - **S: What type of food are you looking for?**
- Dialogue state:
  - venue\_type = restaurant
  - food\_type = None
  - price\_range = None

# User says

Dialogue state is used to track the progress of the dialogue

- Turn 2:
  - S: What type of food are you looking for?
- Dialogue state:
  - venue\_type = restaurant
  - food\_type = None
  - price\_range = None
- U: inform(food\_type=Chinese)

# Dialogue state update

Dialogue state is used to track the progress of the dialogue

- Turn 2:
  - S: What type of food are you looking for?

- Dialogue state:
  - venue\_type = restaurant
  - **food\_type = Chinese**
  - price\_range = None



Dialogue state update

# Ontology

- Used to define the structure of a dialogue state and dependencies between variables
- It can simplify building a new SDS for a new domain

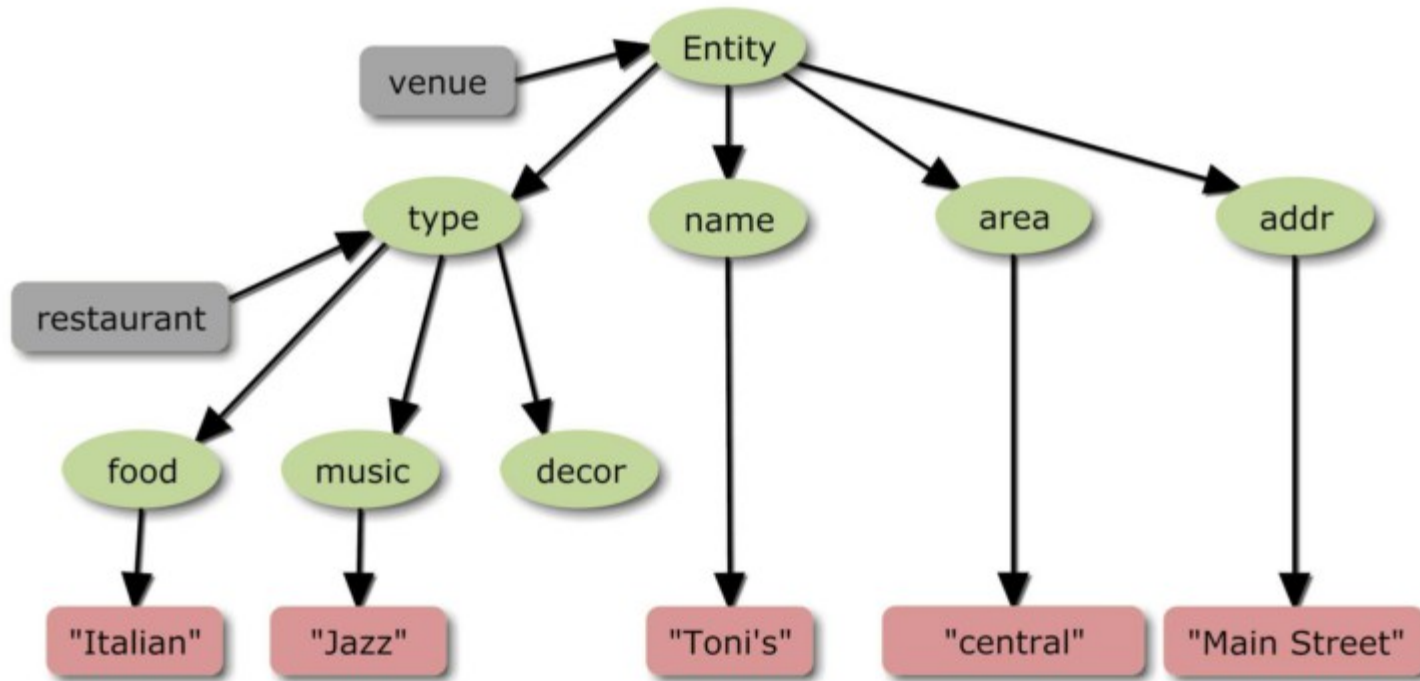


Figure 2: Example Tree for TownInfo Application

# Ontology

## # top level tasks

```
task -> find (-entity, -method,  
-discourseAct);
```

## # define main entities in domain

```
entity -> venue(type, +area, +near,  
-addr, -phone, -postcode, *reviews,  
*rating, +pricerange, -price);
```

## # places to eat

```
type -> restaurant(+food);  
type -> pub(childrenallowed,  
hasinternet, hastv);  
type -> coffeeshop(food);
```

## # attributes

```
pricerange = ( ffree | cheap"  
| moderate | expensive");
```

```
area = (girton|kingshedges|arbury|  
...  
citycentre|riverside|castlehill);
```

```
food = ( "American"  
...  
| "Chinese takeaway");
```

```
hasinternet = ( true | false);  
hastv = ( true | false);  
childrenallowed = ( true | false);
```

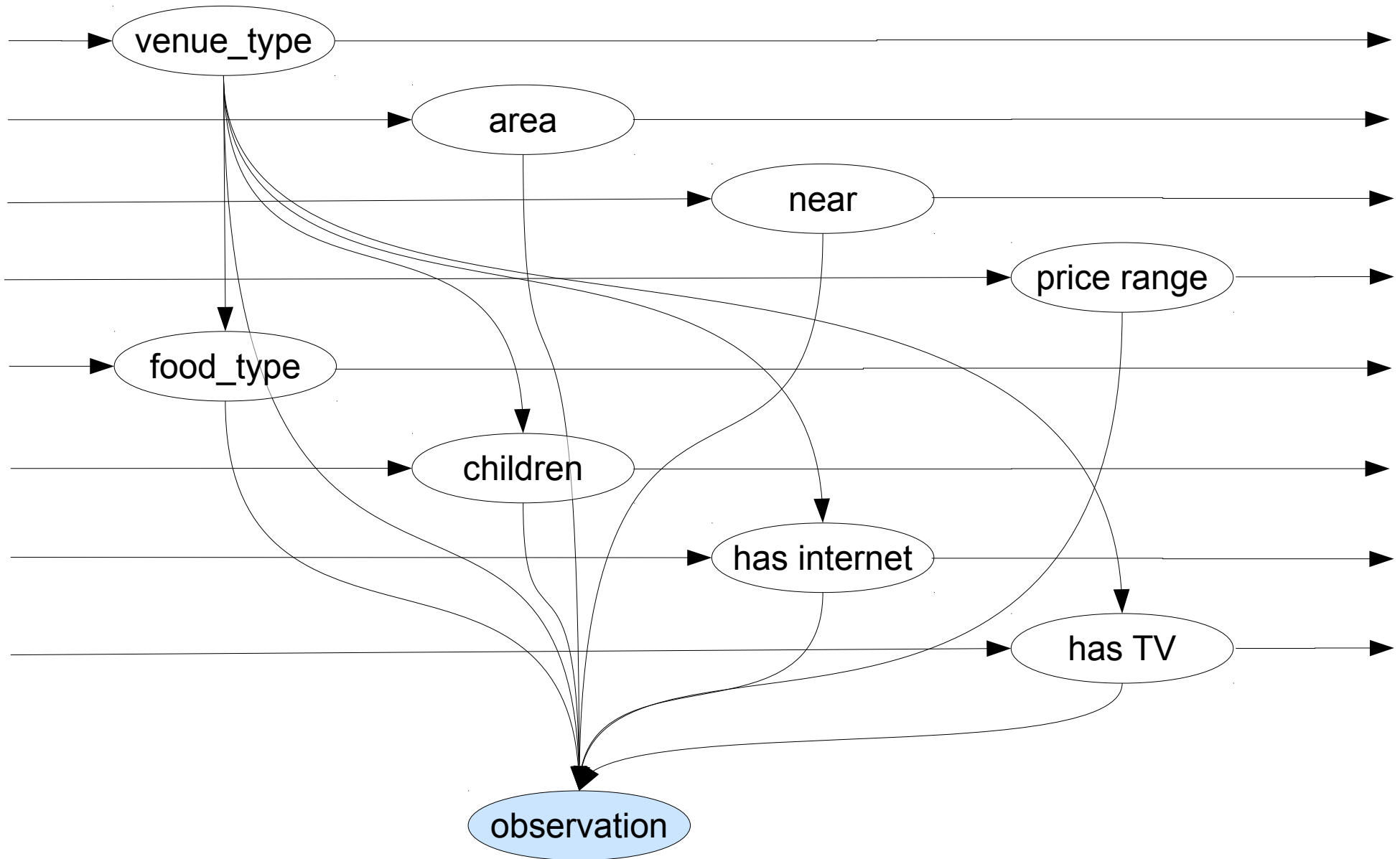
## # descriptive lexical types

```
addr = ();  
phone = ();  
postcode = ();  
price = ();  
rating = ();  
reviews = ();
```

# Ontology

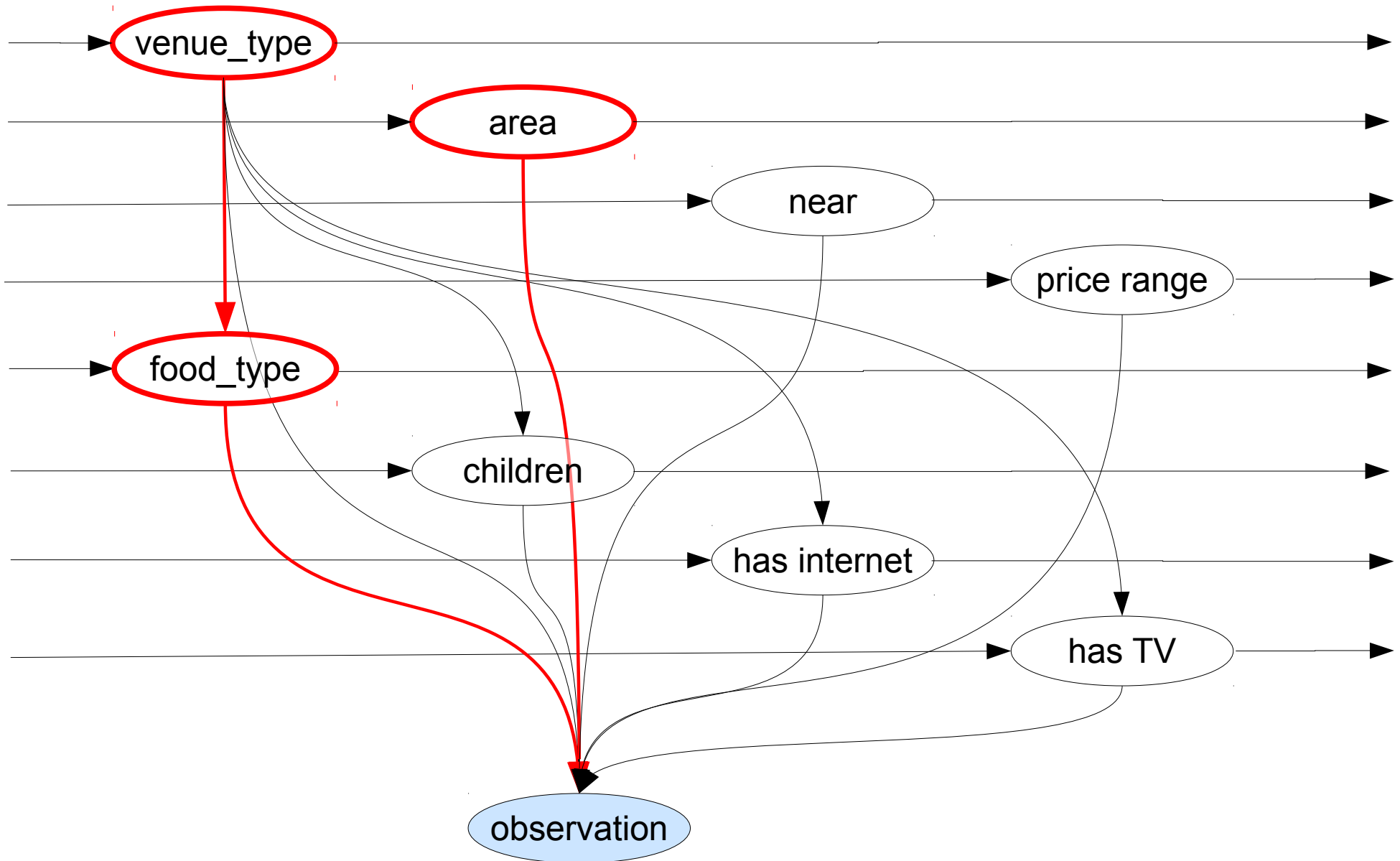
- Defines
  - all concepts in the domain
  - their dependencies
  - should be **requested** by the system (+)
  - should **not** be **requested** by the system (-)
- Dependencies:
  - some concepts are applicable only for some values of parents concepts' values
  - e.g.
    - `hastv` only if `venue_type = pub`
    - `food` only if `venue_type = restaurant`

# TownInfo influence network



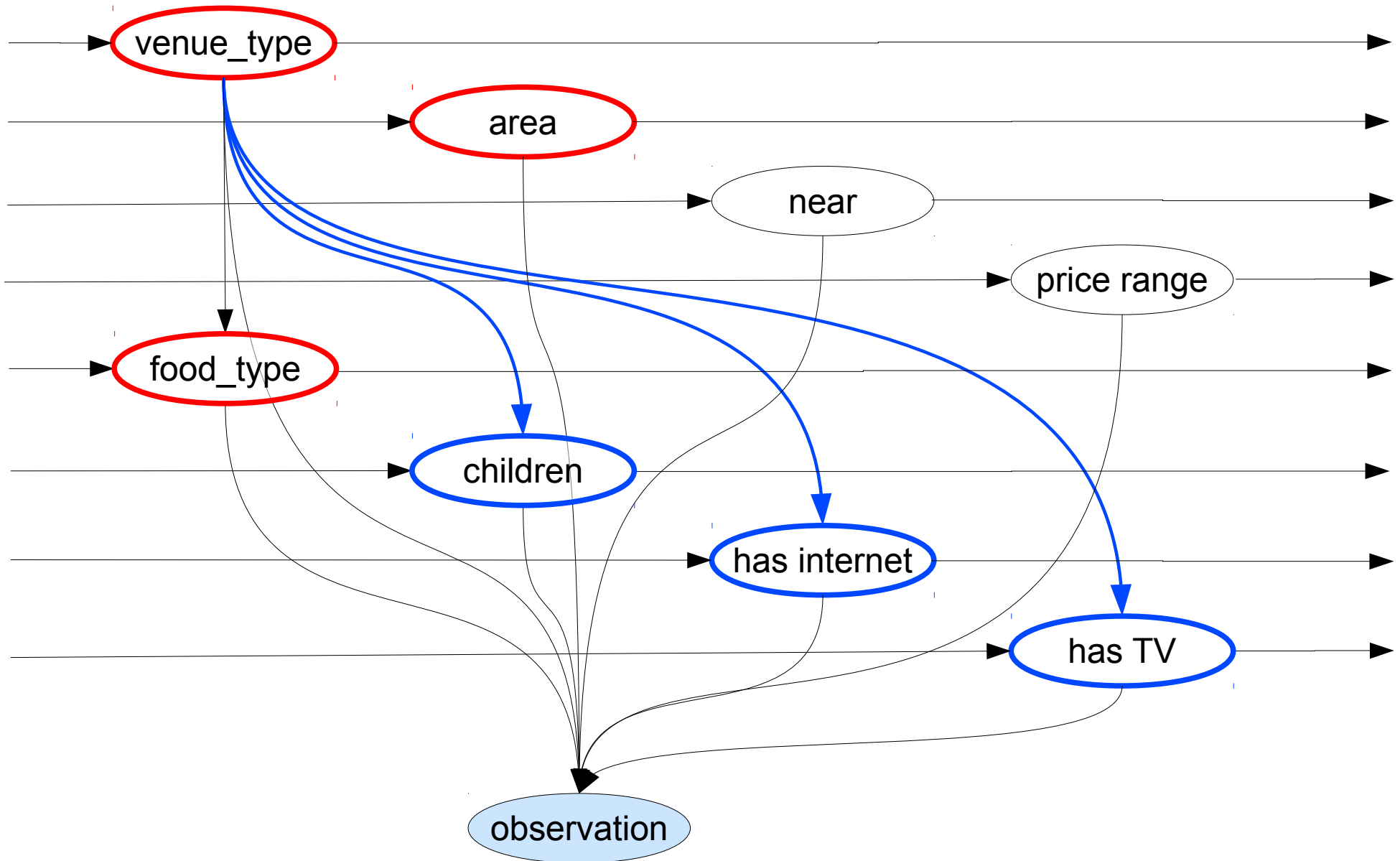


# Store new information



inform(**food\_type**=Chinese)&inform(**area**=centre)

# Update old information

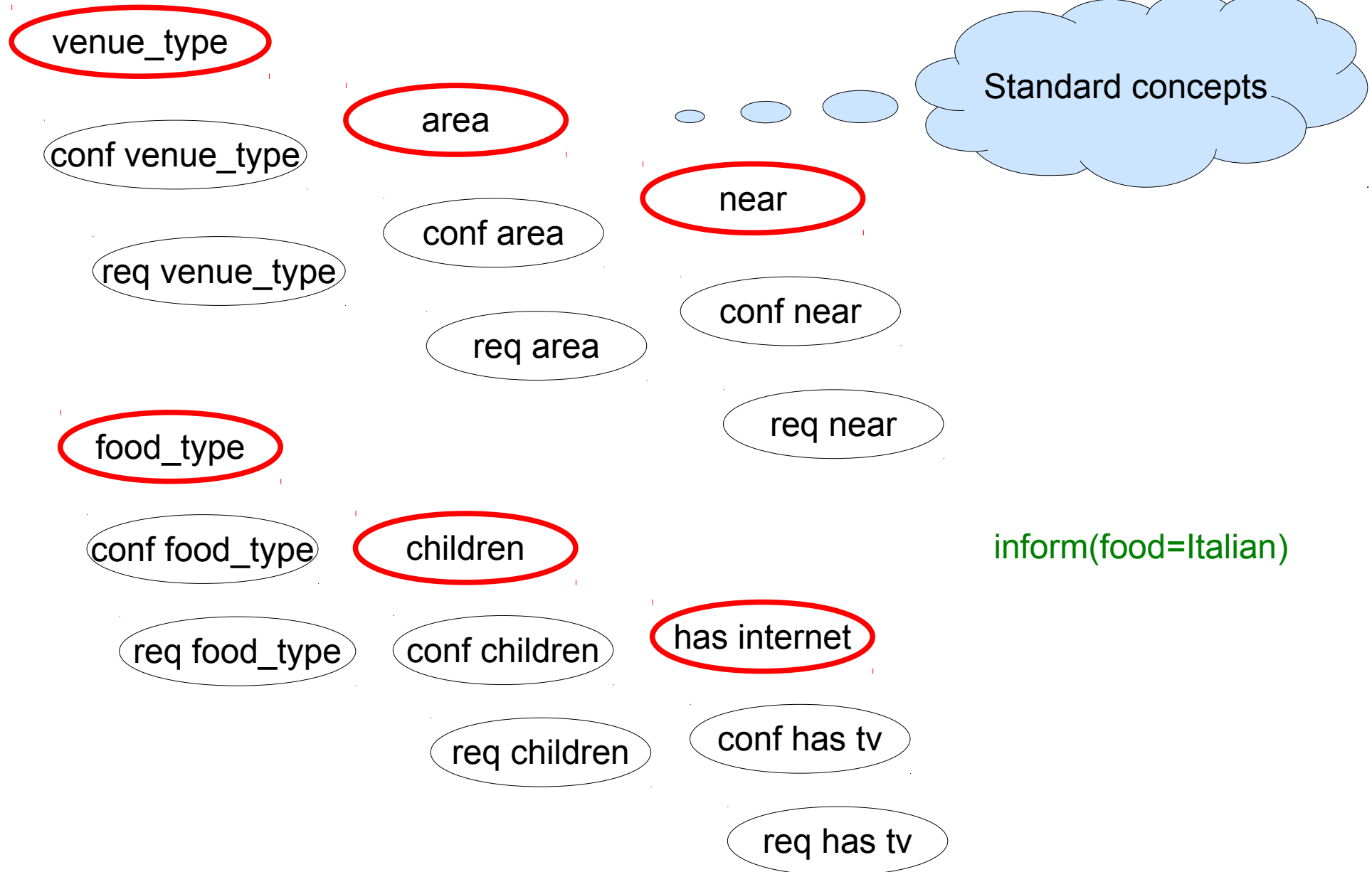


inform(food\_type=Chinese)&inform(area=centre)

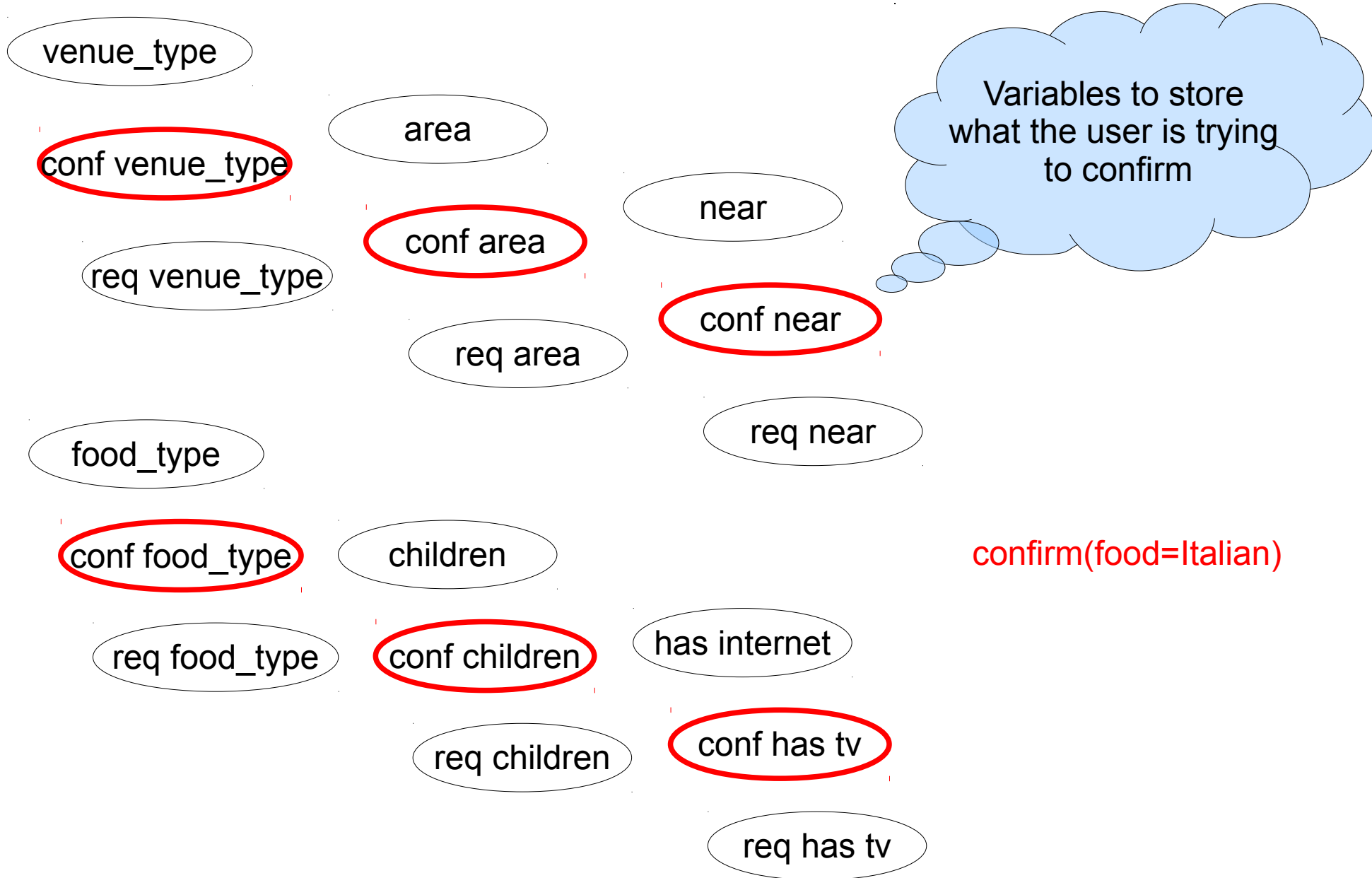
# Dialogue state contains much more

- It should also store information about the context
- E.g.
  - what user requested
  - what user confirms
  - what system already informed about
  - what system confirmed

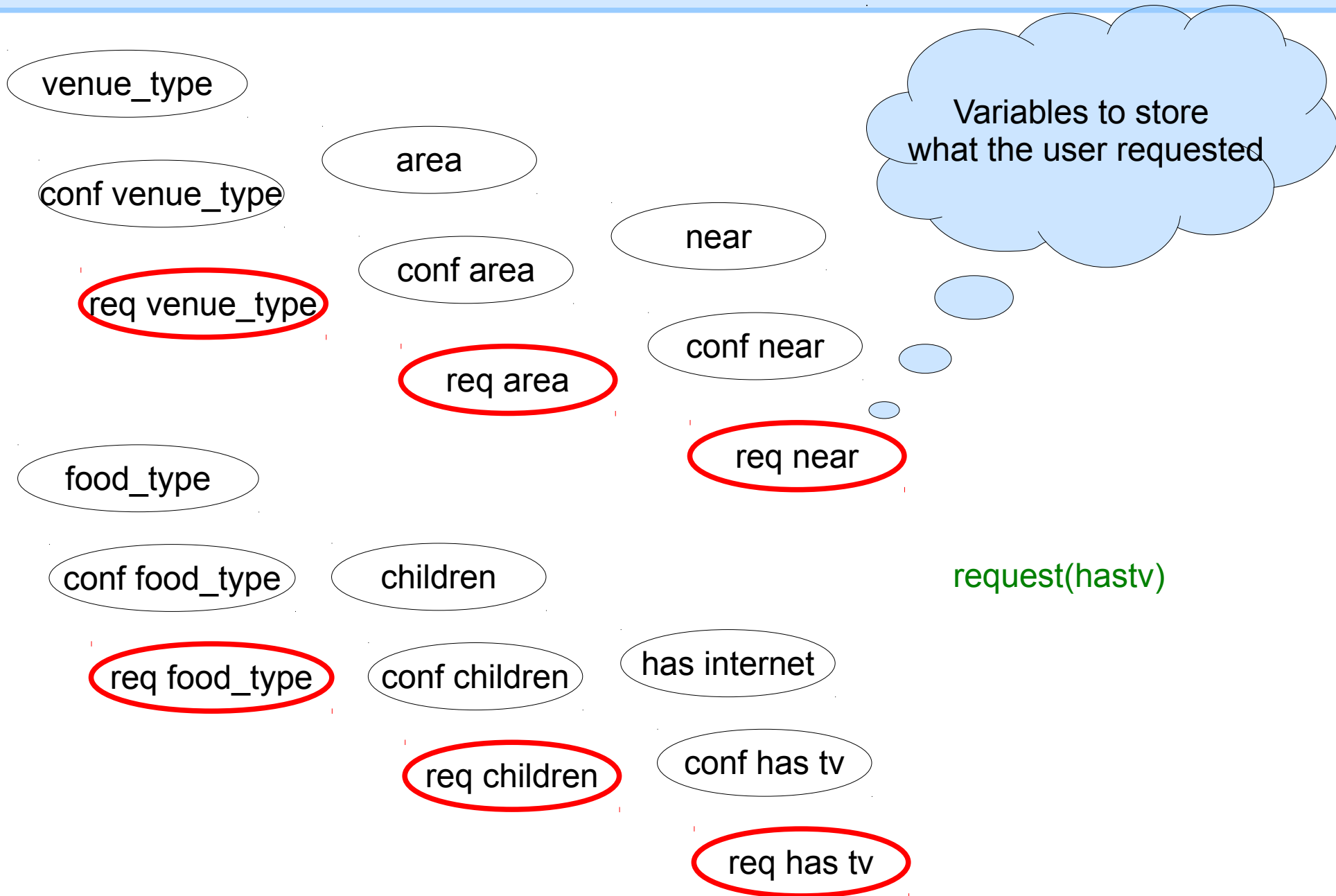
# Expanded state



# Expanded state



# Expanded state



# Expanded state

- Should also contain a variable for handling other semantic context
- “context node” possible values:
  - hello
  - bye
  - ack
  - thank you
  - request more
  - repeat
  - restart

# Further expanded state

- Should store all info we gave to the user
- E.g.
  - names of the offered venues
  - the order of the offered venues
- To be able handle e.g. references
  - “No, I would the prefer the previous bar. Give me the address.”
- To offer an alternative
  - “Do you have anything else?”
  - give a user a venue which was not talked about yet



# Summary so far

- How to define dialogue state
- Use of domain independent ontology
- The state must support general aspects of a dialogue
  - such as negotiation

# Problem with this approach

- ASR is unreliable
  - WER 30% in real-life environment
- SLU makes mistakes too
  - Some utterances are ambiguous
- Example:
  - User said:
    - I am looking for an **inexpensive** hotel.
  - ASR decoded:
    - I am looking for an **expensive** hotel.
  - SLU output:
    - `inform(venue_type=hotel, price_range=expensive)`

# Example

- U1: inform(venue\_type=restaurant)
- Dialogue state:
  - venue\_type = restaurant
  - food\_type = None
  - price\_range = None
  - stars = None

# Example

- U1: inform(venue\_type=restaurant)
- U2: inform(stars=five)

- Dialogue state:

- **venue\_type = restaurant**
- food\_type = None
- price\_range = None
- **stars = five**



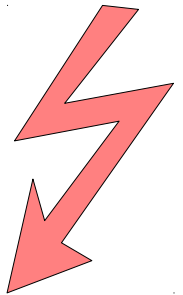
Contradiction



Restaurants usually do not have stars

# Attempts to fix the problem

- Detect contradictions
  - Confirm the contradicting information
- Reject input with low confidence score
  - `inform(venue_type=restaurant,stars=five) [0.3]`
- How to set the threshold?
- Are we loosing some information?
  - What if we reject something 10x?

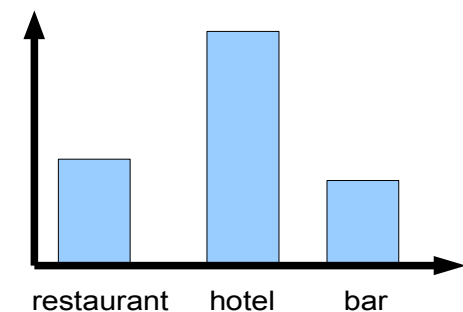
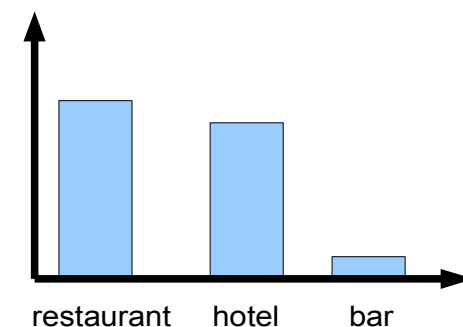


# Statistical Spoken Dialogue Systems

- Main goal is to make the dialogue systems
  - robust
  - natural
- Robustness
  - accumulation information over multiple turns
  - accumulating information from N-best list
- Naturalness
  - trained from data / interaction with users

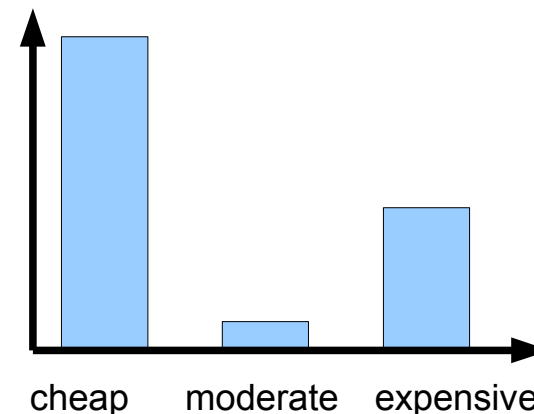
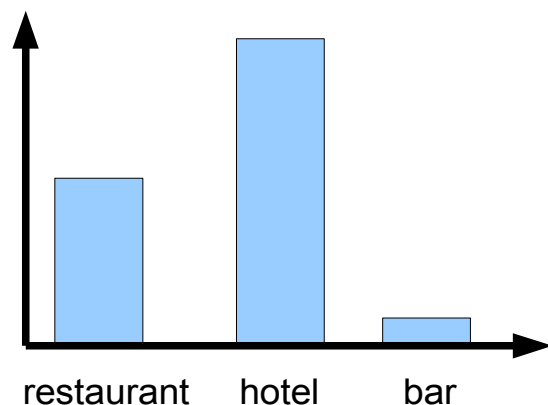
# Information from multiple turns

- Accumulating the probabilities
- Turn 1:
  - `inform(venue_type=restaurant)` [ 0.5]
  - `inform(venue_type=hotel)` [0.4]
- Turn 2:
  - `inform(venue_type=bar)` [0.4]
  - `inform(venue_type=hotel)` [0.4]



# Information from multiple hypotheses

- Accumulating the probabilities
- N-best list:
  - `inform(venue_type=restaurant)&inform(price_range=cheap)` [ 0.3]
  - `inform(venue_type=hotel)&inform(price_range=expensive)` [0.3]
  - `inform(venue_type=hotel)&inform(price_range=cheap)` [0.2]





# POMDP motivation

- The previous behaviour can be elegantly handled by
  - Partially Observable Markov Decision Process (POMDP)
- Context can be used to resolve some ambiguity
- Context models can be optimised with respect to the domain in hand

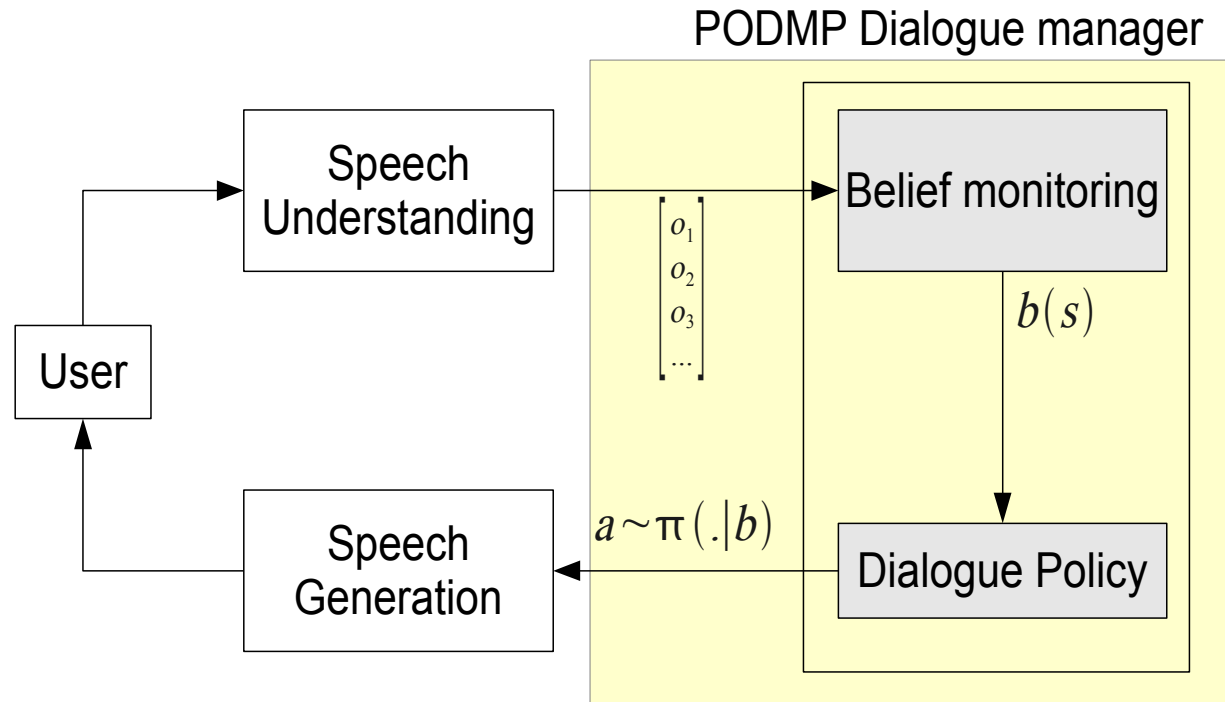
# POMDP dialogue system #1

- POMDP DM can be naturally divided into two components:
  - belief monitoring
    - tracks what a user said – a distribution over all states
  - action selection
    - decides what to do next – a discrete action
- When a POMDP system is trained using reinforcement learning then it is optimised to maximise a reward function
  - e.g. average success rate, length of a dialogue, both, etc.



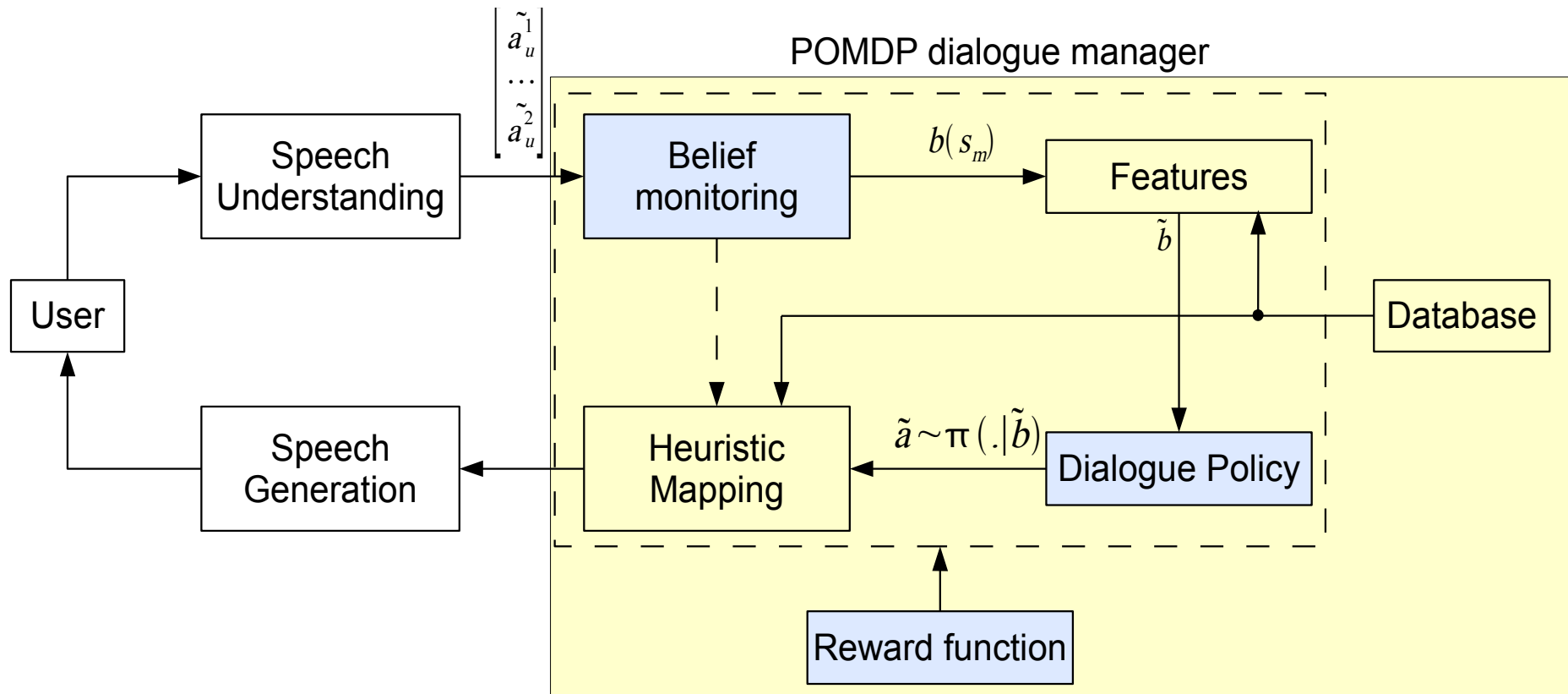
We will talk about this later.

# POMDP dialogue system #2



- Instead of tracking the state  $\mathbf{s}$ , the dialogue manager maintains a distribution over all states:  $\mathbf{b}(\mathbf{s})$
- Policy explicitly takes into the account in the uncertainty in  $\mathbf{b}(\mathbf{s})$

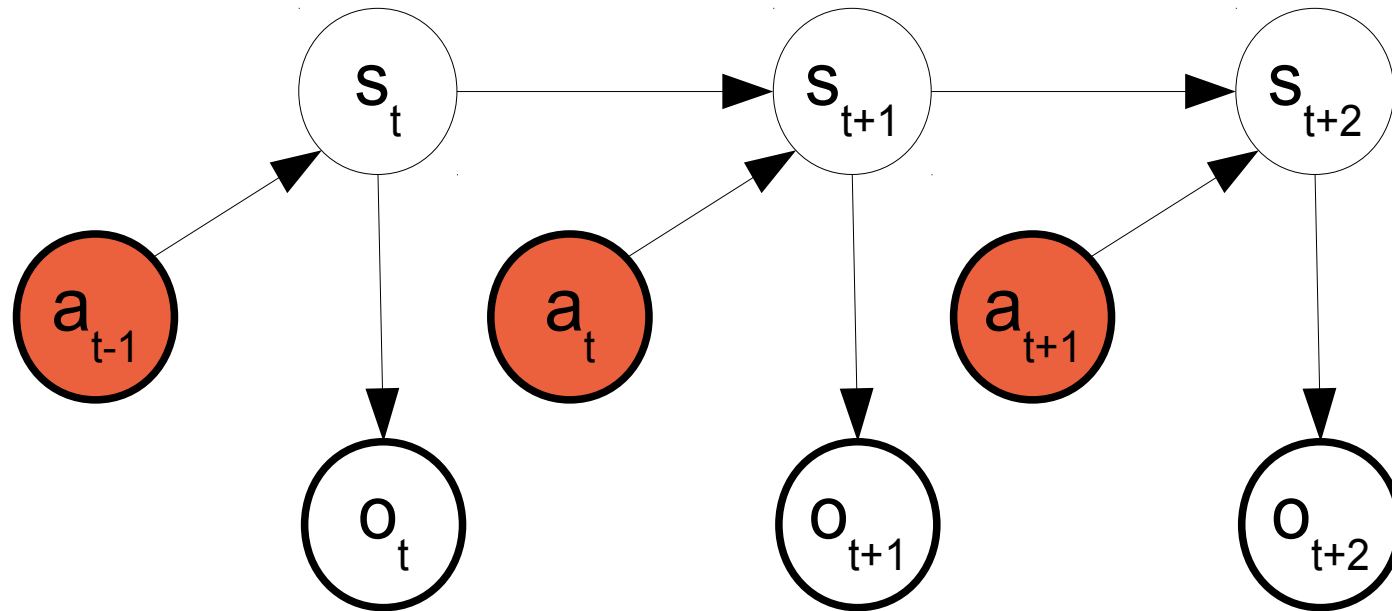
# POMDP dialogue system approximations



Each of the components uses its own set of approximation techniques to achieve real-time performance

# Belief monitoring

- Maintains prob. distribution over all possible states:  $\mathbf{b}(\mathbf{s})$
- Belief state  $\mathbf{b}(\mathbf{s})$ 
  - can be modelled as input-output HMM

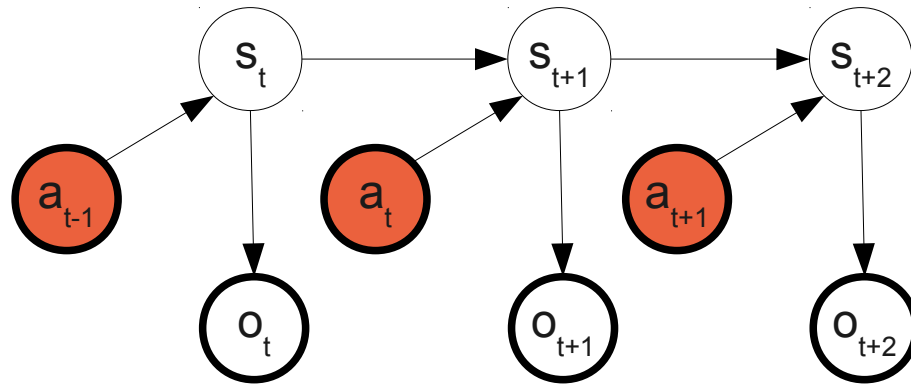


- $a$  – the system's action - output
- $o$  – user's actions - input

# Naive belief monitoring

- The exact inference is trivial

$$b(s; \tau) \propto p(o_t | s_t; \tau) \sum_{s_{t-1}} p(s_t | a_{t-1}, s_{t-1}; \tau) b(s_{t-1}; \tau)$$



- The estimate depends on the dialogue model
  - parametrized by  $\tau$
- Problem is that there are too many states
  - e.g. 10 slots each with 10 values gives  $10^{10}$  distinct states

# Speeding things up

- Some researchers:
  - **enumerate the most likely states and prune the others**
  - **mixture model belief monitoring**
    - J. Henderson and O. Lemon, “**Mixture model POMDPs for efficient handling of uncertainty in dialogue management,**” pp. 73-76, Jun. 2008.
  - **group similar states**
    - S. Young, M. Gasic, S. Keizer, F. Mairesse, J. Schatzmann, B. Thomson and K. Yu (2010). “**The Hidden Information State Model: a practical framework for POMDP-based spoken dialogue management.**”
  - **particle filters**
    - J. D. Williams, “**USING PARTICLE FILTERS TO TRACK DIALOGUE STATE,**” in Proceedings of IEEE ASRU, 2007.
  - **belief propagation**
    - B. Thomson and S. Young (2010). “**Bayesian update of dialogue state: A POMDP framework for spoken dialogue systems.**”

# Enumerating and pruning

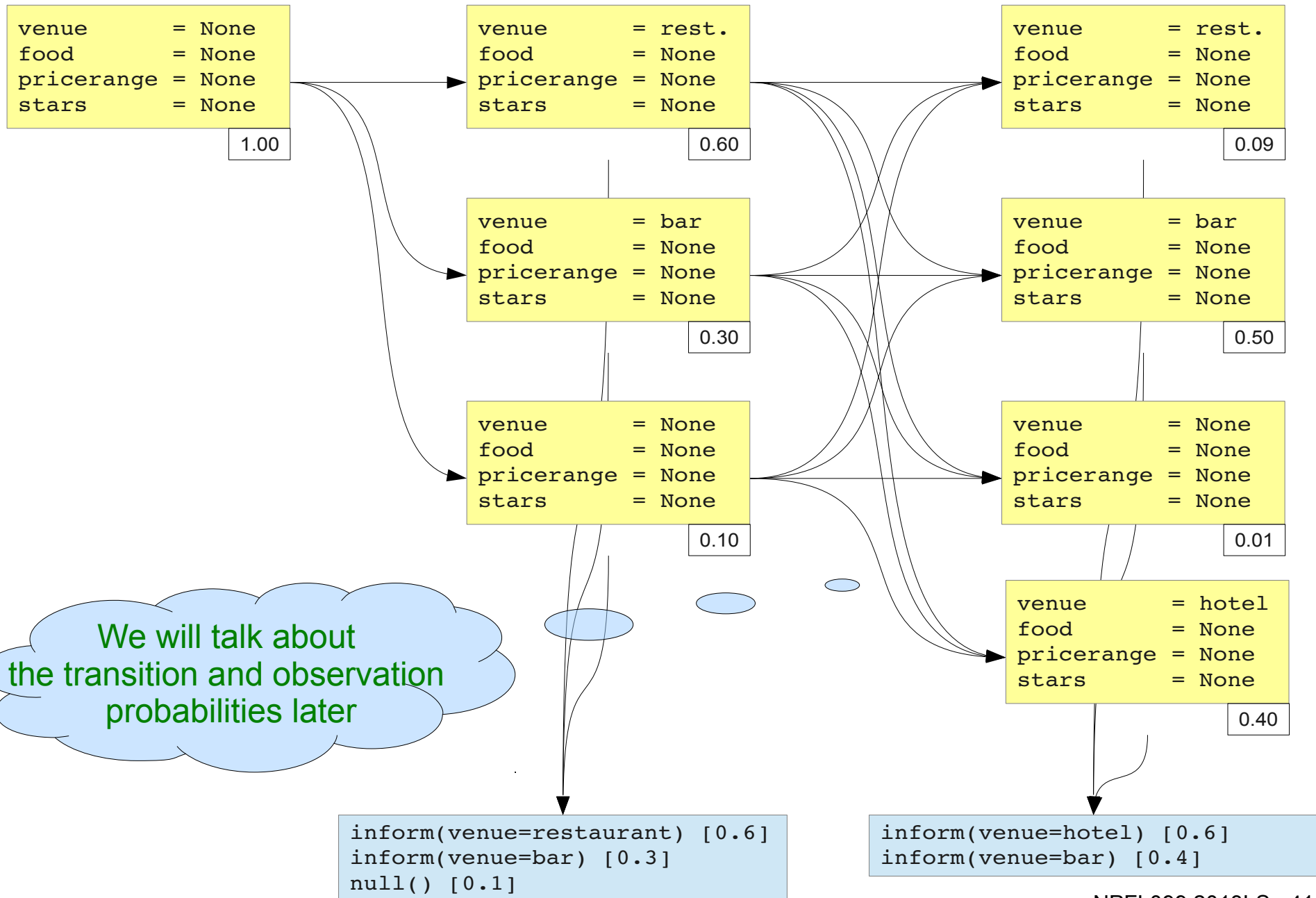
- Pruning less likely states
  - states with low probability are ignored
  - however, even after pruning, there are too many states

$$\begin{array}{l} s_1 = 0.050 \\ s_2 = 0.100 \\ s_3 = 0.110 \\ s_4 = 0.300 \\ \del{s_5 = 0.001} \\ \dots \end{array}$$

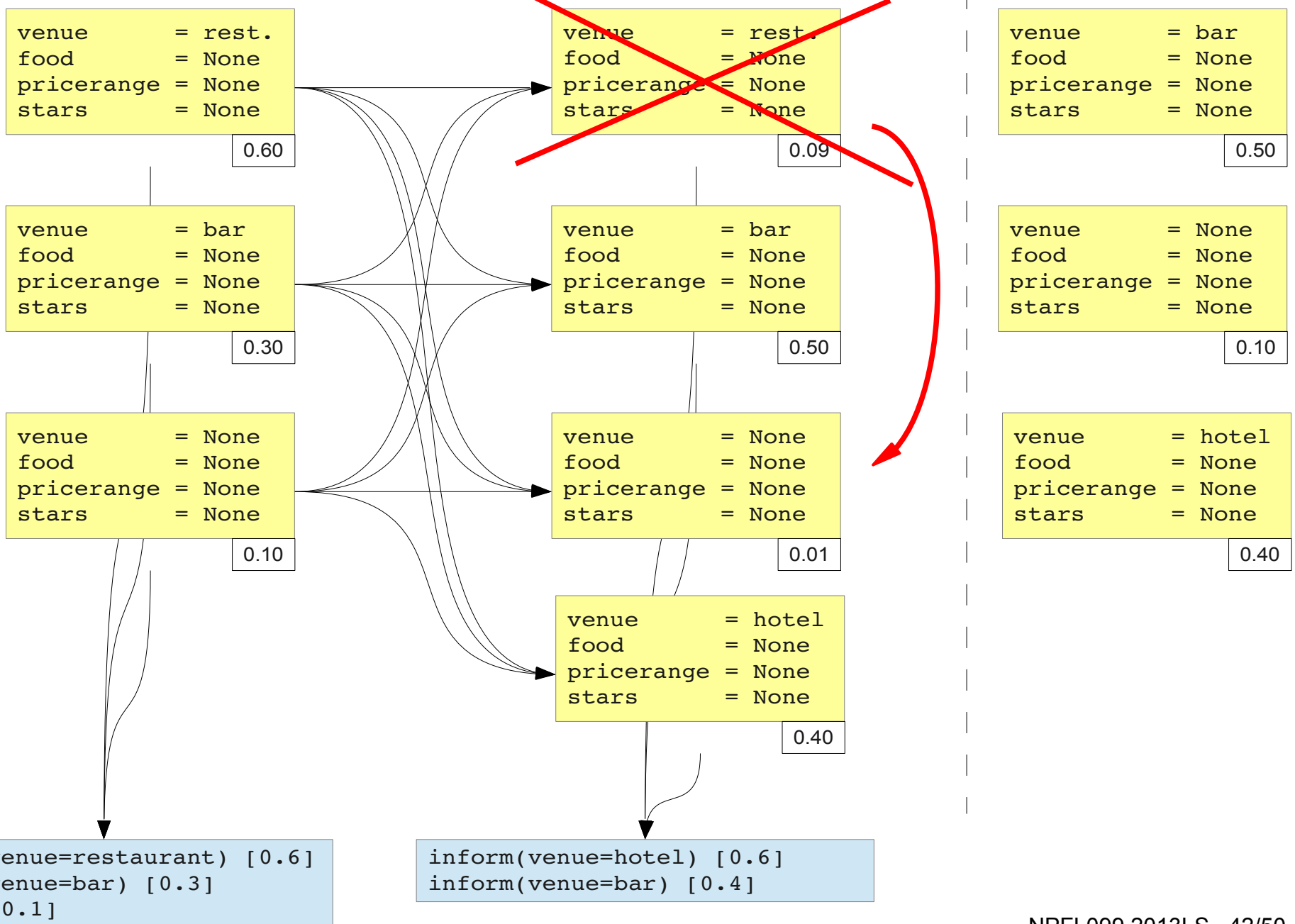
- Enumerate only states supported by observation hypotheses
  - T1:
    - `inform(venue=restaurant)` [0.6]
    - `inform(venue=bar)` [0.3]



# Enumerating



# Pruning



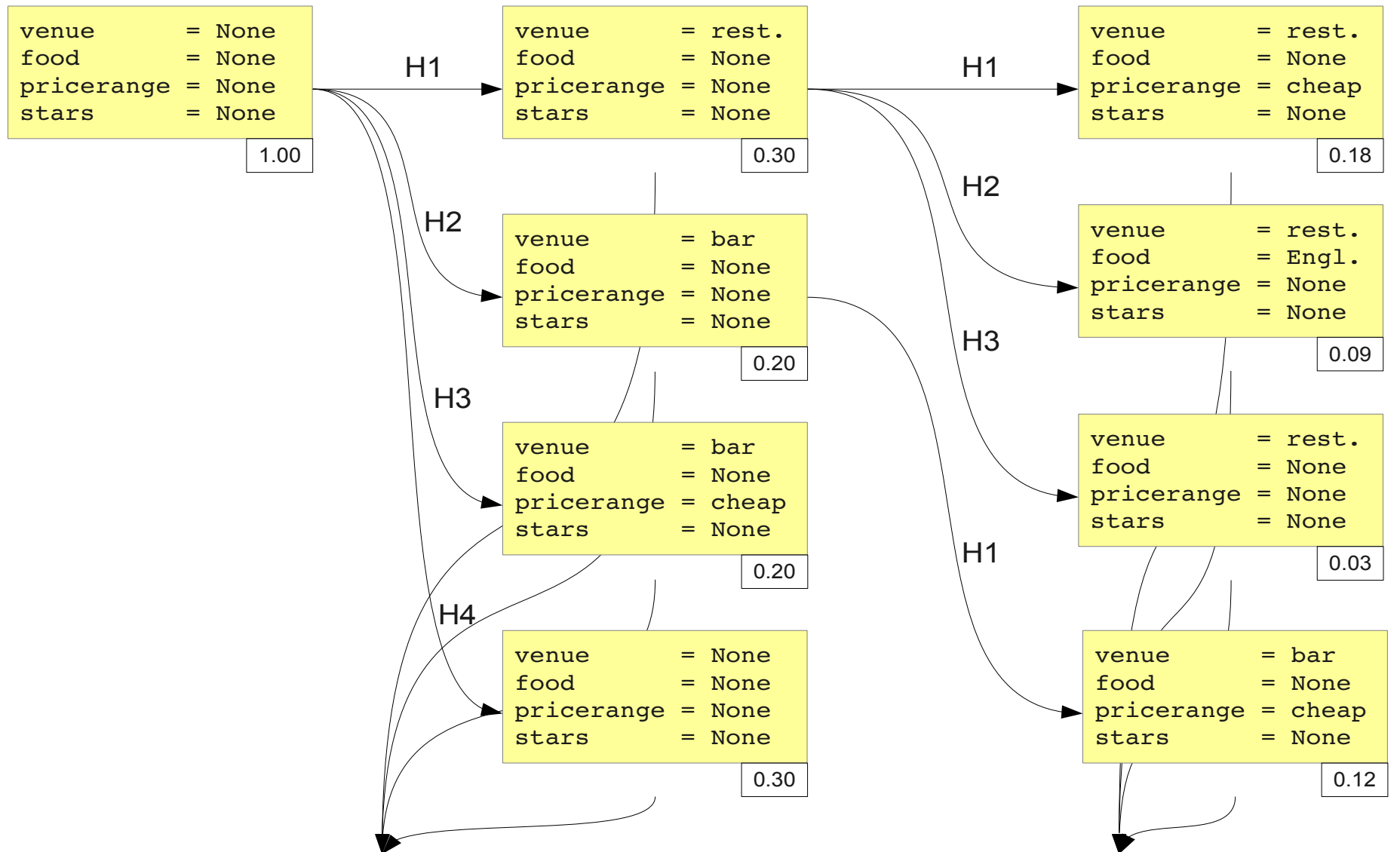
# Dialogue model

- Model parameters can be estimated from some annotated data
  - very tedious
- Transition model:  $p(s_{t+1} | s_t, a_t)$ 
  - models dynamics of the evolution of the states
  - from a particular state to states generated based on the input observations/hypotheses
- Observation model:  $p(o_t | s_t)$ 
  - models probability of the observations given a state

# Mixture model belief monitoring

- Updating the dialogue state for each input hypothesis separately
- State probability depends only on observations
- Transitions allowed only between the “compatible states” given the observation
- Can be viewed as maintaining a set of dialogue managers executing in parallel

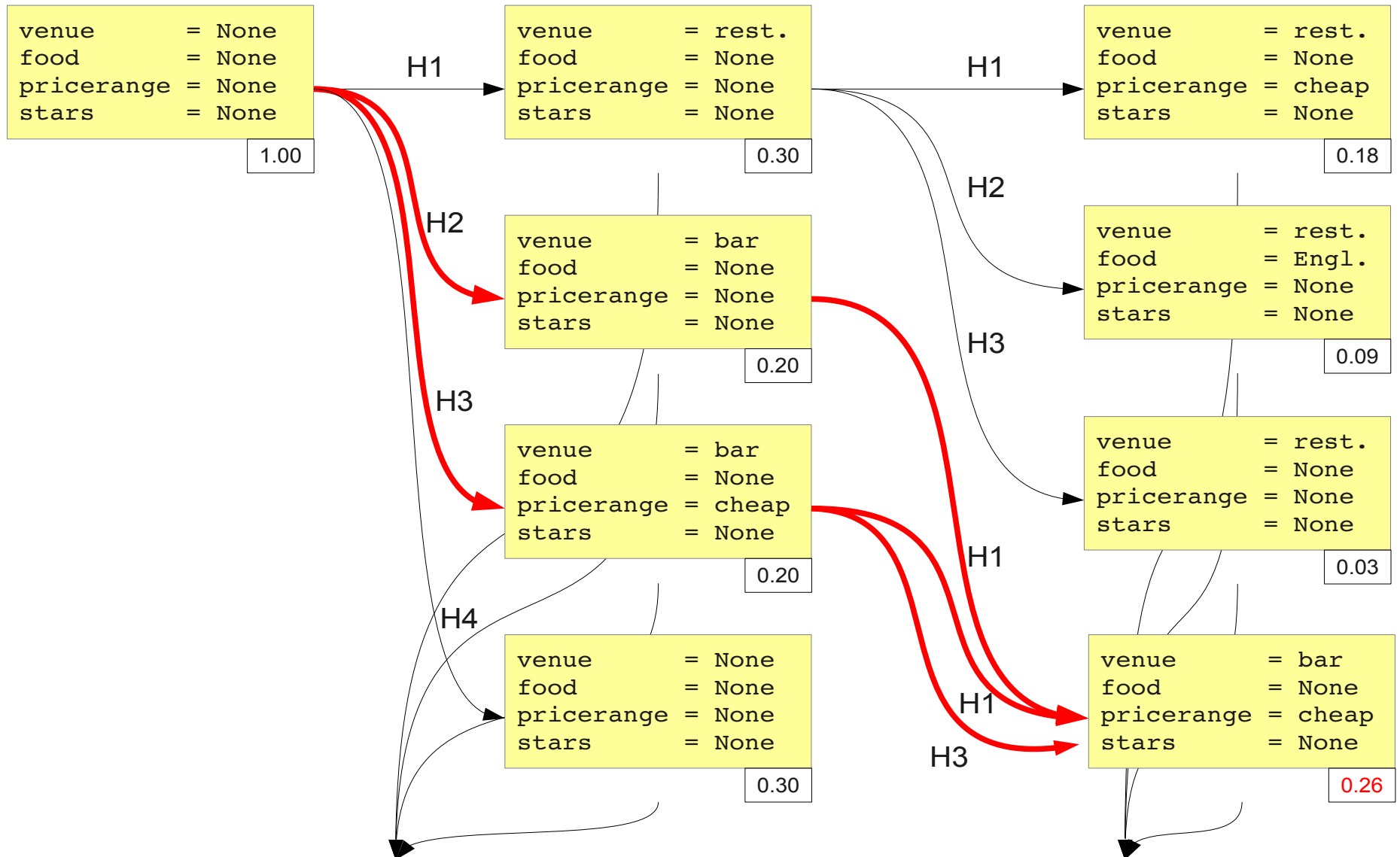
# Enumerating



H1: inform(venue=restaurant) [0.3]  
 H2: inform(venue=bar) [0.2]  
 H3: inform(venue=bar)&inform(pricerange=cheap) [0.2]  
 H4: null() [0.3]

H1: inform(pricerange=cheap) [0.6]  
 H2: inform(food=English) [0.3]  
 H3: null() [0.1]

# State merging



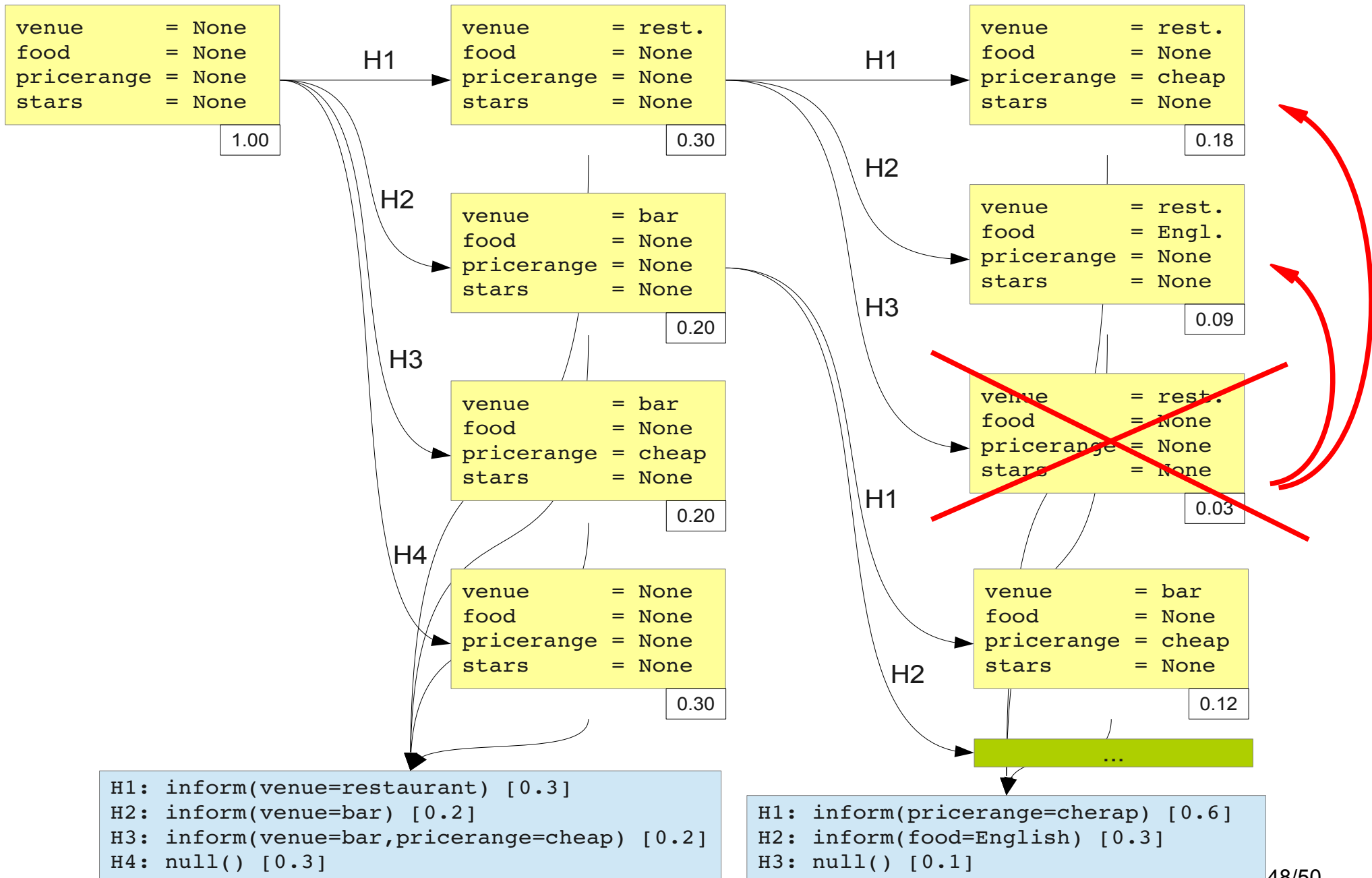
H1: inform(venue=restaurant) [0.3]  
 H2: inform(venue=bar) [0.2]  
 H3: inform(venue=bar)&inform(pricerange=cheap) [0.2]  
 H4: null() [0.3]

H1: inform(pricerange=cheap) [0.6]  
 H2: inform(food=English) [0.3]  
 H3: null() [0.1]

# Pruning

- First
  - find similar states (e.g. share filled slots but not history, share some filled slots)
  - prune the less likely
  - add the pruned probability mass to the kept states
- Second
  - Prune states with low probability
  - Redistribute the probability mass
    - e.g. add the pruned probability mass to the initial state
- Pruning should not simply remove a hypothesis and renormalise, it should **redistribute** the probability of a pruned hypothesis to similar hypotheses

# Pruning





# Dialogue model

- Choice of the model can greatly simplify computation
- All prob. information comes only from the observation model
- Transition model:
  - $\sum_{s_{t+1} \in C(s_t, o_t)} p(s_{t+1} | s_t, a_t) = 1.0$
  - from a particular state to states generated based on the input observations/hypotheses
  - probability is uniform for all compatible states
- Observation model:
  - $p(o_t | s_t)$
  - the model is further factorised to prevent data sparsity

# Thank you!

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