Introduction to Machine Learning NPFL 054

http://ufal.mff.cuni.cz/course/npf1054

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Outline

- Combining classifiers into ensembles general scheme
- Generating random samples by bootstrapping
- Bagging vs. boosting
- Bagging example classifier
- Random Forests
- Simple boosting the regression case
- Classification with AdaBoost

Ensemble classifiers – a motivation exercise

Consider the following task – we have a binary classification problem and a number of predictors, each with error less than 0.5. Will the resulting majority voting ensemble have an error lower than the single classifers?

Depends on the accuracy and the diversity of the base learners!

Illustrative example

Particular settings – assume that you have

- 21 classifiers
- each with error p = 0.3
- their outputs are *statistically independent*

Compute the error of the ensemble under these conditions!

Solution of the exercise

How many classifiers will produce error output?

Key idea: The number of them will be binomially distributed! \sim Bi(21, 0.3)

```
> plot(0:21, dbinom(0:21, 21, 0.3))
> dbinom(11, 21, 0.3)
[1] 0.01764978
> pbinom(10, 21, 0.3)
[1] 0.9736101
```



Conslusion: Accuracy of the ensemble will be more than 97.3 %!

NPFL054, 2017

Hladká & Holub

General scheme of combining classifiers



Resampling can be used as a way to produce diversity among base learners

- Distribute the training data into K portions
- Run the learning process to get K different models
- Collect the output of the K models use a combining function to get a final output value

- New data sets *Data*₁, ..., *Data*_K are drawn from *Data* with replacement, each of the same size as the original *Data*, i.e. *n*.
- In the *i*-th step of the iteration, *Data_i* is used as a training set, while the examples {x | x ∈ Data ∧ x ∉ Data_i} form the test set.
- The probability that we pick an instance is 1/n, and the probability that we do not pick an instance is 1 1/n. The probability that we do not pick it after *n* draws is $(1 1/n)^n \approx e^{-1} \doteq 0.368$.
- It means that for training the system will not use 36.8% of the data, and the error estimate will be pessimistic. So the solution is to repeat the process many times.

Same algorithm, different classifiers

Combining classifiers to improve the performance

Ensemble methods - key ideas

- combining the classification results from different classifiers to produce the final output
- using (un)weighted voting
- different training data e.g. bootstrapping
- different features
- different values of the relevant paramaters
- performance: complementarity \longrightarrow potential improvement

Two fundamental approaches

- **Bagging** works by taking a bootstrap sample from the training set
- **Boosting** works by changing the weights on the training set

- Bagging: each predictor is trained independently
- Boosting: each predictor is built on the top of previous predictors trained

- Like bagging, boosting is also a voting method. In contrast to bagging, boosting actively tries to generate complementary learners by training the next learner on the mistakes of the previous learners.

Combining multiple learners

- the more **complementary** the learners are, the more useful their combining is
- the simpliest way to combine multiple learners is voting
- in weighted voting the voters (= base-learners) can have different weights

Unstable learning

- learning algorithm is called unstable if small changes in the training set cause large differences in generated models
- typical unstable algorithm is the decision trees learning
- bagging or boosting techniques are a natural remedy for unstable algorithms

- Bagging is a voting method that uses slightly different training sets (generated by bootstrap) to make different base-learners. Generating complementary base-learners is left to chance and to unstability of the learning method.
- Generally, bagging can be combined with any approach to learning.

Bootstrap AGGregatING

- **1** for $i \leftarrow 1$ to K do
- **2** $Train_i \leftarrow bootstrap(Data)$
- **3** $h_i \leftarrow \text{TrainPredictor}(Train_i)$

Combining function

- Classification: $h_{final}(\mathbf{x}) = MajorityVote(h_1(\mathbf{x}), h_2(\mathbf{x}), \dots, h_K(\mathbf{x}))$
- Regression: $h_{final}(\mathbf{x}) = Mean(h_1(\mathbf{x}), h_2(\mathbf{x}), \dots, h_K(\mathbf{x}))$

- an ensemble method based on decision trees and bagging
- builds a number of random decision trees and then uses voting
- introduced by L. Breiman (2001), then developed by L. Breiman and A. Cutler
- very good (state-of-the-art) prediction performance
- a nice page with description
 www.stat.berkeley.edu/~breiman/RandomForests/cc_home.htm
- important: Random Forests helps to
 - avoid overfitting (by random sampling the training data set)
 - select important/useful features (by random sampling the feature set)

The algorithm for building a tree in the ensemble

- **1** Having a training set of the size *n*, sample *n* cases at random with replacement, and use the sample to build a decision tree.
- 2) If there are M input features, choose a less number $m \ll M$. When building the tree, at each node a random sample of m features is selected as split candidates from the full set of M available features. Then the best split on these m features is used to split the node. A fresh sample of m features is taken at each split.

-m is fixed for the whole procedure

3 Each tree is grown to the largest extent possible. There is no pruning.

The more trees in the ensemble, the better. There is no risk of overfitting!

- a recent extension of the original Random Forest
 - introduced by Houtao Deng and George Runger (2012)
- produces a compact feature subset
- provides an effective and efficient feature selection solution for many practical problems
- overcomes the weak spot of the ordinary RF: Random Forest importance score is biased toward the variables having more (categorical) values
- a useful page: https://sites.google.com/site/houtaodeng/rrf
 - a presentation
 - a sample code
 - links to papers
 - a brief explanation of the difference between RRF and guided RRF

- randomForest: Breiman and Cutler's random forests for classification and regression
 - Classification and regression based on a forest of trees using random inputs.
- RRF: Regularized Random Forest
 - Feature Selection with Regularized Random Forest. This package is based on the 'randomForest' package by Andy Liaw. The key difference is the RRF function that builds a regularized random forest.
 - http://cran.r-project.org/web/packages/RRF/index.html
- party: A Laboratory for Recursive Partytioning
 - a computational toolbox for recursive partitioning
 - cforest() provides an implementation of Breiman's random forests
 - extensible functionality for visualizing tree-structured regression models is available

Boosting combines the outputs of many "weak" classifiers ("rules of thumb") to produce a powerfull "commitee."

Motivation

- How to extract rules of thumb that will be the most useful?
- How to combine moderately accurate rules of thumb into a single highly accurate prediction rule?

Basic idea

- Boosting is a method that produces a very accurate predictor by combining rough and moderately accurate predictors.
- It is based on the observation that finding many rough predictors (rules of thumb) can be easier than finding a single, highly accurate predictor.

Simple boosting with regression trees

1 Initialization: Set h(x) = 0 and $r_i = y_i$ for all i = 1, ..., n in the training set

2 For b = 1,..., B, repeat
(a) Fit a tree h^b with only d splits to the training set (X, r)
(b) Update h by adding the new tree

$$h(x) \leftarrow h(x) + \lambda h^b(x)$$

(c) Update the residuals

$$r_i \leftarrow r_i - \lambda h^b(x_i)$$

Output the boosted model

$$h(x) = \sum_{b=1}^{B} \lambda h^{b}(x)$$

- The number of trees *B*
- The shinkage parameter
- The number d of splits in each tree
 trees with just d = 1 split are called "stumps"

AdaBoost is a boosting method that repeatedly calls a given weak learner, each time with different distribution over the training data. Then we combine these weak learners into a strong learner.

- originally proposed by Freund and Schapire (1996)
- great success
 - "AdaBoost with trees is the best off-the-shelf classifier in the world." (Breiman 1998)
 - "Boosting is one of the most powerful learning ideas introduced in the last twenty years." (Hastie et al, 2009)

Key questions

- How to choose the distribution?
- How to combine the weak predictors into a single predictor?
- How many weak predictors should be trained?

Schapire's strategy: Change the distribution over the examples in each iteration, feed the resulting sample into the weak learner, and then combine the resulting hypotheses into a voting ensemble, which, in the end, would have a boosted prediction accuracy.

AdaBoost.M1 (Freund and Schapire, 1997) is the most popular boosting algorithm

• Consider a binary classification task with the training data

$$Data = \{ \langle \mathbf{x}_i, y_i \rangle : \mathbf{x}_i \in \mathbf{X}, y_i \in \{-1, +1\}, i = 1, \dots, n \}$$

• We need to define distribution \mathcal{D} over *Data* such that $\sum_{i=1}^{n} \mathcal{D}_{i} = 1$.

• Assumption: a weak classifier h_t has the property

 $\operatorname{error}_{\mathcal{D}}(h_t) < 1/2.$

Adaboost (Adaptive Boosting) — key idea

Classifiers are trained on weighted versions of the original training data set, and then combined to produce a final prediction



Final hypothesis $h(x) = \operatorname{sign} \sum_{t=1}^{M} \alpha_t h_t(x)$, where α_t are computed by the boosting algorithm, and weight the contribution of each respective h_t

AdaBoost – iterative algorithm

- Initialize the training distribution $\mathcal{D}_1(i) = 1/n$ for $i = 1, \ldots, n$
- At each step t
 - Learn h_t using \mathcal{D}_t : find the weak classifier h_t with the minimum weighted sample error $\operatorname{error}_{\mathcal{D}_t}(h_t) = \sum_{i=1}^{n} \mathcal{D}_t(i) \,\delta(h(\mathbf{x}_i) \neq y_i)$
 - Set weight α_t of h_t based on the sample error

$$\alpha_t = \frac{1}{2} \ln \left(\frac{1 - \operatorname{error}_{\mathcal{D}_t}(h_t)}{\operatorname{error}_{\mathcal{D}_t}(h_t)} \right)$$

• Update the training distribution

 $\mathcal{D}_{t+1} = \mathcal{D}_t \, e^{-\alpha_t y_i h_t(\mathbf{x}_i)} / Z_t$ where Z_t is a normalization factor

• Stop when impossible to find a weak classifier being better than chance

• Output the final classifier $h_{\text{final}}(\mathbf{x}) = \operatorname{sign} \sum_{t=1} \alpha_t h_t(\mathbf{x})$

Constructing \mathcal{D}_t

• On each round, the weights of incorrectly classified instances are increased so that the algorithm is forced to focus on the hard training examples.

•
$$\mathcal{D}_1(i) = 1/n$$
 for $i = 1, ..., n$

• given
$$\mathcal{D}_t$$
 and h_t (i.e. update \mathcal{D}_t):

$$\mathcal{D}_{t+1}(i) = \frac{\mathcal{D}_t(i)}{Z_t} \cdot \begin{cases} e^{-\alpha_t} & \text{if } y_i = h_t(x_i) \\ e^{\alpha_t} & \text{if } y_i \neq h_t(x_i) \end{cases} = \frac{\mathcal{D}_t(i)}{Z_t} e^{-\alpha_t y_i h_t(x_i)},$$

where Z_t is normalization constant $Z_t = \sum_i \mathcal{D}_t(i) e^{-\alpha_t y_i h_t(x_i)}$

• α_t measures the importance that is assigned to h_t

As the iterations proceed, examples that are difficult to classify correctly receive ever-increasing influence

Weights of the base learners α_t

- $error_{\mathcal{D}_t}(h_t) < \frac{1}{2} \Rightarrow \alpha_t > 0$
- the smaller the error, the bigger the weight of the (weak) base learner
- the bigger the weight, the more impact on the (strong) resulting classifier

$$error_{\mathcal{D}_t}(h_1) < error_{\mathcal{D}_t}(h_2) \Longrightarrow \alpha_1 > \alpha_2$$

•
$$\mathcal{D}_{t+1} = \frac{1}{Z_t} \mathcal{D}_t e^{-\alpha_t y_i h_t(\mathbf{x}_i)}$$

The weights of correctly classified instances are reduced while weights of misclassified instances are increased.

Multiclass problem – generalization of the two-class case

• Assume classification task where $Y = \{y_1, \dots, y_k\}$

 $h_t: X \to Y,$

$$\mathcal{D}_{t+1}(i) = \frac{\mathcal{D}_t(i)}{Z_t} \cdot \begin{cases} e^{-\alpha_t} & \text{if } y_i = h_t(\mathbf{x}_i) \\ e^{\alpha_t} & \text{if } y_i \neq h_t(\mathbf{x}_i) \end{cases}$$
$$h_{final}(\mathbf{x}) = \operatorname{argmax}_{y \in Y} \sum_{\{t \mid h_t(\mathbf{x}) = y\}} \alpha_t.$$