

# Introduction to Machine Learning

## NPFL 054

<http://ufal.mff.cuni.cz/course/npfl054>

**Barbora Hladká**

**Martin Holub**

{Hladka | Holub}@ufal.mff.cuni.cz

Charles University,  
Faculty of Mathematics and Physics,  
Institute of Formal and Applied Linguistics

# Programming questions

- **(Hierarchical) clustering**
  - Feature scaling
  - NLI data set (75 documents, 5 languages)
- **Gradient descent algorithm**
  - Find a minimum of a function using Gradient Descent Algorithm (simple illustration)
- **Auto data set**
  - Compute Pearson's correlation coefficients for mpg, displacement, weight, horsepower, acceleration in the Auto data set
  - Draw boxplots to visualize comparison mpg by origin, mpg by model year, and weight by origin
- **Linear regression**
  - Auto data set, target attribute: mpg

## Different ranges and units of features

- Is the engine displacement more significant than mpg/cylinders/acceleration?

```
> str(Auto)
```

```
'data.frame':  392 obs. of  9 variables:
 $ mpg          : num  18 15 18 16 17 15 14 14 14 15 ...
 $ cylinders    : num   8  8  8  8  8  8  8  8  8  8 ...
 $ displacement: num  307 350 318 304 302 429 454 440 455 390 ...
 $ horsepower  : num  130 165 150 150 140 198 220 215 225 190 ...
 $ weight       : num  3504 3693 3436 3433 3449 ...
 $ acceleration: num   12 11.5 11 12 10.5 10 9 8.5 10 8.5 ...
 $ year        : num   70  70  70  70  70  70  70  70  70  70 ...
 $ origin      : Factor w/ 3 levels "USA","Europe",...: 1 1 1 1 1 1 1 1 1 1 ...
 $ name       : Factor w/ 304 levels "amc ambassador brougham",...: 49 36 231
```

# Feature scaling

## Scaling

- normalization  $z = \frac{x - x_{min}}{x_{max} - x_{min}}$ ,  
i.e., the feature values are shifted and rescaled so that they end up ranging between 0 and 1  
 $z \in \langle 0, 1 \rangle$
- standardization  $z = \frac{x - \bar{x}}{sd_x}$ ,  
i.e., the feature values are centered around the mean with a unit standard deviation  
 $\bar{z} = 0, sd_z = 1$

## Useful especially for

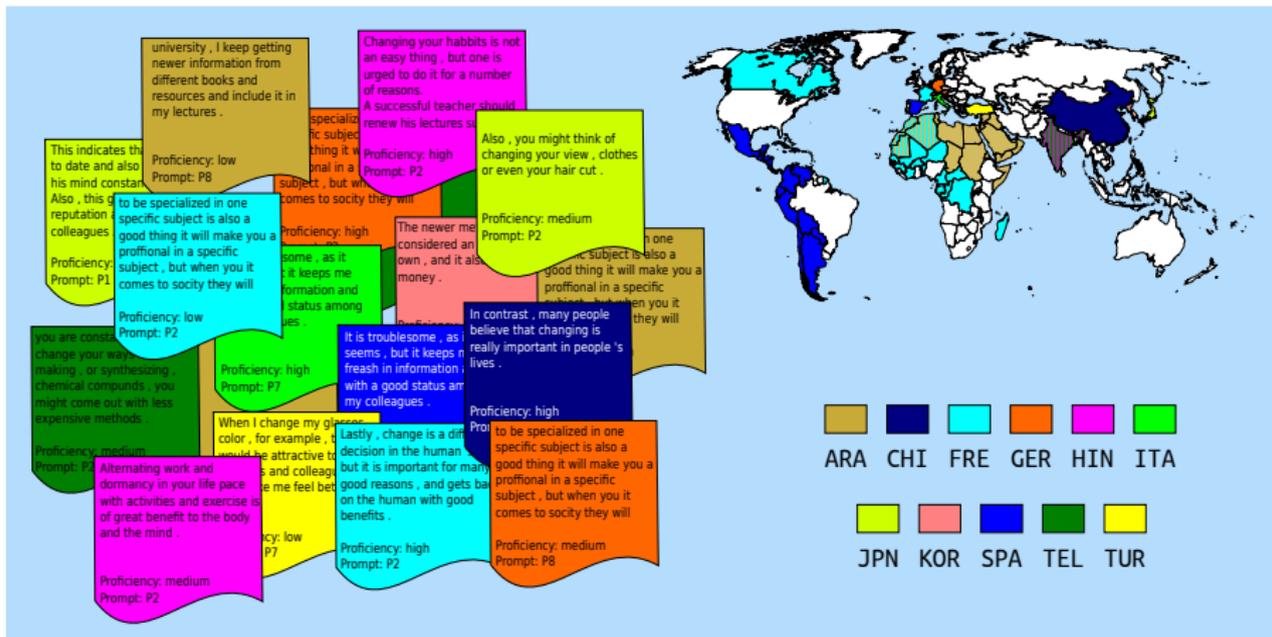
- Gradient Descent Based Algorithms
- Distance based algorithms



```
> head(scale(Auto[,c('mpg', 'displacement', 'weight')]))
```

	mpg	displacement	weight
1	-0.6977467	1.075915	0.6197483
2	-1.0821153	1.486832	0.8422577
3	-0.6977467	1.181033	0.5396921
4	-0.9539925	1.047246	0.5361602
5	-0.8258696	1.028134	0.5549969
6	-1.0821153	2.241772	1.6051468

# Native language identification task (NLI)



Identifying the native language (L1) of a writer based on a sample of their writing in a second language (L2)

## Our data

- **L1s:** Arabic (ARA), Chinese (ZHO), French(FRA), German (DEU) Hindi (HIN), Italian (ITA), Japanese (JPN), Korean (KOR), Spanish (SPA), Telugu (TEL), Turkish (TUR)
- **L2:** English
- **Real-world objects:** For each L1, 1,000 texts in L2 from The ETS Corpus of Non-Native Written English (former TOEFL11), i.e.  $Train \cup DevTest$
- **Target class:** L1

*More detailed info is available at the course website.*

## Topic

Most advertisements make products seem much better than they really are

## Sample text

now a days the publicity is the best way to promoted a produt and if you want to sale a product you should bring some information that makes , that the people who is seeing the advertisements make sure that the product very good and in the future this person could buy it .

**L1 = Spanish**

# Linear regression

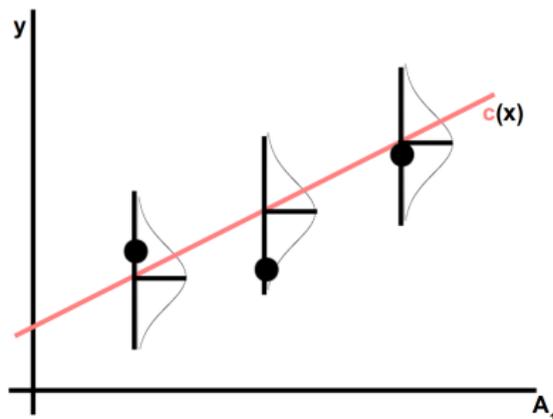
## Random error term

- numerical target attribute  $Y$
- $\mathbf{y} = \mathbf{X}\Theta^T + \epsilon$
- random error term  $\epsilon$  having mean zero, very often unobserved

# Linear regression

## Random error term

- $\epsilon_i = y_i - \Theta^\top \mathbf{x}_i$  (true target value  $y_i$ , expected value  $\Theta^\top \mathbf{x}_i$ )
- Assumption like: At each value of  $A_1$ , the output value  $y$  is subject to random error  $\epsilon$  that is normally distributed  $N(0, \sigma^2)$



# Linear regression

## Random error term

- $\epsilon_i = y_i - \Theta^\top \mathbf{x}_i$  (true target value  $y_i$ , expected value  $\Theta^\top \mathbf{x}_i$ )
- residual  $e_i = y_i - \hat{\Theta}^\top \mathbf{x}_i$  is an estimate of  $\epsilon_i$