Introduction to Machine Learning NPFL 054

http://ufal.mff.cuni.cz/course/npf1054

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Outline

- Evaluation of binary classification (cntnd) ROC curve
- Model complexity, overfitting, bias and variance
- Regularization Ridge regression, Lasso
 - Linear regression
 - Logistic regression

Confusion matrix

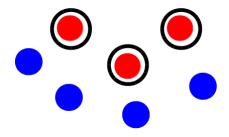
		Predicted class		
		Positive	Negative	
True class	Positive	True Positive (TP)	False Negative (FN)	Р
	Negative	False Positive (FP)	True Negative (TN)	Ν

Measure	Formula	
Precision	TP/(TP+FP)	
Recall/Sensitivity/TPR	TP/(TP+FN) = TP/P	
Specificity	TN/(TN+FP)	
1-Specificity/FPR	FP/(TN+FP) = FP/N	
Accuracy	(TP+TN)/(TP+FP+TN+FN)	

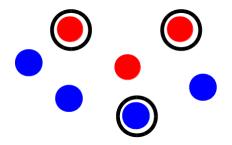
Seven training examples

Classifier's output – examples in black circle are positives, other examples are negatives

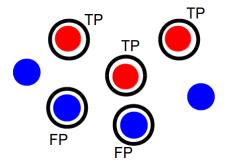
Perfect classifier - no error



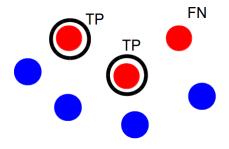
Reality – e.g. 2 miclassified examples sensitivity = 2/3, specificity = 3/4



Reality – e.g. 2 miclassified examples sensitivity = 1, specificity = 1/2

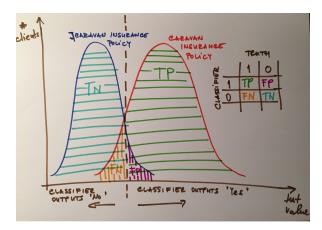


Reality – e.g. 1 miclassified example sensitivity = 2/3, specificity = 1



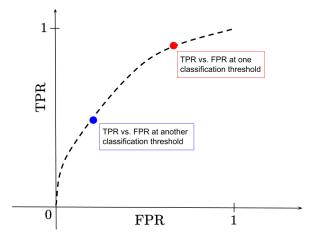
Sensitivity (TPR) vs. specificity (TNR)

- as the sensitivity increases, the specificity decreases and vice versa



Evaluation of binary classifiers ROC curve

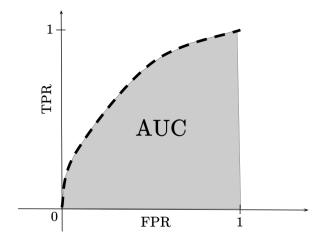
An **ROC curve** plots True Positive Rate vs. False Positive Rate at different classification thresholds where FPR = 1 - TNR = FP/N = FP/(FP+TN)



Evaluation of binary classifiers AUC measure

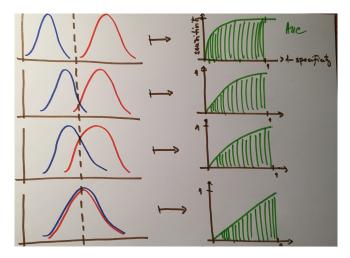
Area Under ROC (= AUC)

is a measure of how good is a distinguishing property of classifier



Evaluation of binary classifiers ROC & AUC

Curves closer to the top-left corner indicate a better performance.

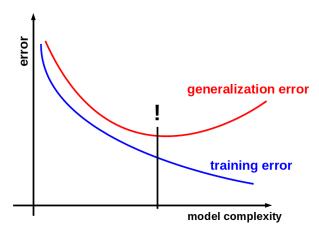


No universal definition

Heading for the regularization $\ldots \textbf{model complexity}$ is the number of hypothesis parameters

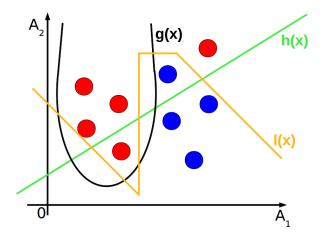
$$\Theta = \langle \theta_0, \ldots, \theta_m \rangle$$

Finding a model that minimizes generalization error ... is one of central goals of the machine learning process



Model complexity

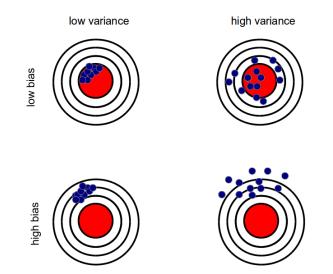
Complexity of decision boundary for classification



- 1 Select a machine learning algorithm
- **2** Get *k* different training sets
- Get k predictors
- Bias measures error that originates from the learning algorithm

 how far off in general the predictions by k predictors are from the true output value
- Variance measures error that originates from the training data
 - how much the predictions for a test instance vary between k predictors

Bias and variance



Generalization error $\operatorname{error}_{\mathcal{D}}(\hat{f})$ measures how well a hypothesis \hat{f} (f is a true target function) generalizes beyond the used training data set, to unseen data with distribution \mathcal{D} . Usually it is defined as follows

- for regression: $\operatorname{error}_{\mathcal{D}}(\hat{f}) = \mathsf{E}[\hat{y}_i y_i]^2$
- for classification: $\operatorname{error}_{\mathcal{D}}(\hat{f}) = \Pr(\hat{y}_i \neq y_i)$

Decomposition of $error_{\mathcal{D}}(\hat{f})$

$$error_{\mathcal{D}}(\hat{f}) = \operatorname{Bias}^2 + \operatorname{Variance}$$

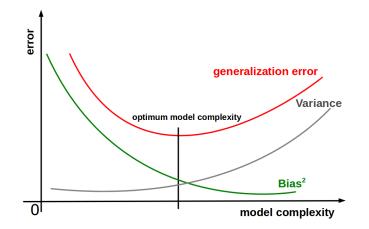
i.e.,

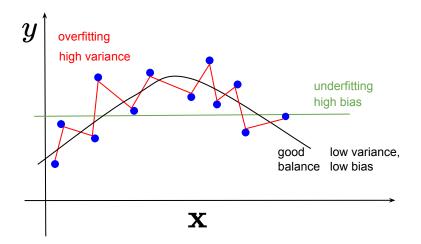
$$(E[\hat{f}(\mathbf{x})] - f(\mathbf{x}))^2 + E[\hat{f}(\mathbf{x}) - E[\hat{f}(\mathbf{x})]]^2$$

where $\hat{f}(\mathbf{x})$ is a predicted value, $E[\hat{f}(\mathbf{x})]$ is average predicted value

Bias and variance

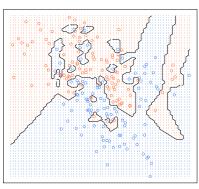
- underfitting = high bias
- overfitting = high variance



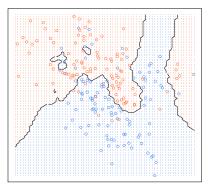


Bias and variance k-Nearest Neighbor

- $\uparrow k \rightarrow$ smoother decision boundary $\rightarrow \downarrow$ variance and \uparrow bias
- $\downarrow k \rightarrow \uparrow$ variance and \downarrow bias



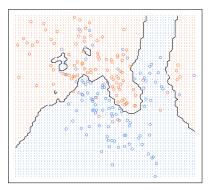
1-nearest neighbour



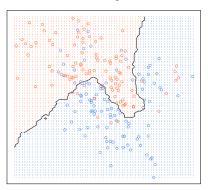
5-nearest neighbour

Bias and variance k-Nearest Neighbor

5-nearest neighbour



15-nearest neighbour



We want a model in between which is

- powerful enough to model the underlying structure of data
- not so powerful to model the structure of the training data

Let's prevent overfitting by complexity regularization,

a technique that regularizes the parameter estimates, or equivalently, shrinks the parameter estimates towards zero.

A machine learning algorithm estimates hypothesis parameters $\Theta = \langle \theta_0, \theta_1, \dots, \theta_m \rangle$ using Θ^* that minimizes loss function L for training data $Data = \{ \langle \mathbf{x}_i, y_i \rangle, \mathbf{x}_i = \langle x_{1i}, \dots, x_{mi} \rangle, y_i \in Y \}$

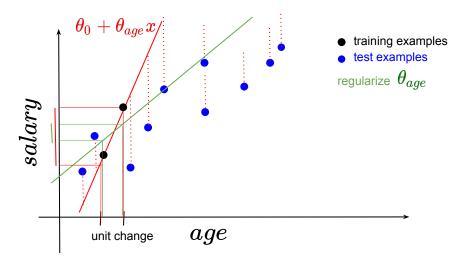
$$\Theta^{\star} = \operatorname{argmin}_{\Theta} L(\Theta)$$

Regularization

 $\Theta_R^{\star} = \operatorname{argmin}_{\Theta} L(\Theta) + \lambda \cdot \mathbf{penalty}(\Theta), \text{ where } \lambda \geq 0 \text{ is a tuning parameter}$

Infact, the penalty is applied to $\theta_1, \ldots, \theta_m$, but not to θ_0 since the goal is to regularize the estimated association between each feature and the target value.

Regularization Motivation



Regularization Ridge regression

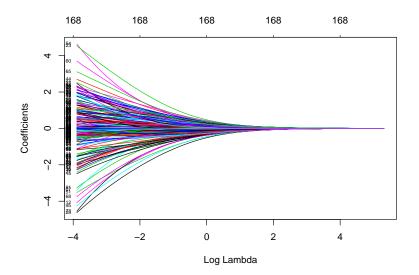
penalty(
$$\Theta$$
) = $\theta_1^2 + \cdots + \theta_m^2 = \ell_2 \operatorname{norm}^2$

- Let $\theta^\star_{\lambda_1},\ldots,\theta^\star_{\lambda_m}$ be ridge regression parameter estimates for a particular value of λ
- Let $\theta_1^{\star}, \ldots, \theta_m^{\star}$ be unregularized parameter estimates

•
$$0 \leq \frac{\theta_{\lambda_1}^{\star^2} + \dots + \theta_{\lambda_m}^{\star^2}}{\theta_1^{\star^2} + \dots + \theta_m^{\star^2}} \leq 1$$

- When $\lambda = 0$, then $\theta^{\star}_{\lambda_i} = \theta^{\star}_i$ for $i = 1, \dots, m$
- When λ is extremely large, then $\theta^{\star}_{\lambda_i}$ is very small for $i = 1, \dots, m$
- When λ between, we are fitting a model and skrinking the parameteres

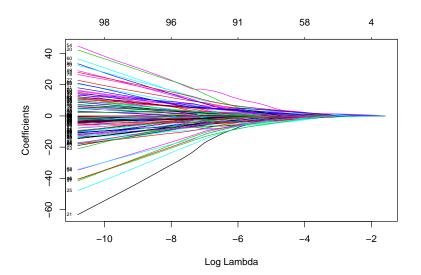
Ridge regression



penalty(
$$\Theta$$
) = $|\theta_1| + \cdots + |\theta_m| = \ell_1$ norm

- Let $\theta^{\star}_{\lambda_1},\ldots,\theta^{\star}_{\lambda_m}$ be lasso regression parameter estimates
- Let $\theta_1^{\star}, \ldots, \theta_m^{\star}$ be unregularized parameter estimates
- When $\lambda = 0$, then $\theta_{\lambda_i}^{\star} = \theta_i^{\star}$ for $i = 1, \dots, m$
- When λ grows, then the impact of penalty grows
- When λ is extremely large, then $\theta^{\star}_{\lambda_i} = 0$ for i = 1, ..., m

Lasso



Ridge regression shrinks all the parameters but eliminates none, while the Lasso can shrink some parameters to zero.

$$\Theta_{R}^{\star} = \operatorname{argmin}_{\Theta} [L(\Theta) + \lambda_{1} \cdot (|\theta_{1}| + \dots + |\theta_{m}|) + \lambda_{2} \cdot (\theta_{1}^{2} + \dots + \theta_{m}^{2})]$$

 $0 \leq \lambda_1, \lambda_2$ are tuning parameters

!!! In glmnet package

$$\Theta_{R}^{\star} = \operatorname{argmin}_{\Theta} L(\Theta) + \lambda(\alpha(|\theta_{1}| + \dots + |\theta_{m}|) + (1 - \alpha)(\theta_{1}^{2} + \dots + \theta_{m}^{2}))$$

$$0 \le \alpha \le 1$$

$$f(\mathbf{x}) = \theta_0 + \theta_1 x_1 + \dots + \theta_m x_m$$

$$L(\Theta) = RSS = \sum_{i=1}^{n} (f(\mathbf{x}_i) - y_i)^2$$

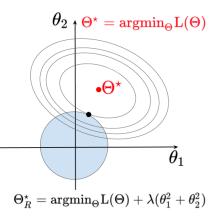
 $\Theta_{R}^{\star} = \operatorname{argmin}_{\Theta}[RSS + \lambda \cdot \mathsf{penalty}(\Theta)]$

Ridge regression Alternative formulation

$$\Theta_R^{\star} = \operatorname*{argmin}_{\Theta} \sum_{i=1}^n (f(\mathbf{x}_i) - y_i)^2$$

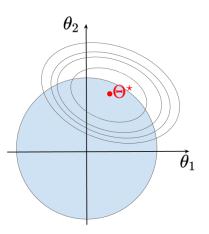
subject to
$$heta_1^2 + \dots + heta_m^2 \leq s$$

- the gray circle represents the feasible region for Ridge regression
- the contours represent different RSS values for the unregularized model



Ridge regression Alternative formulation

 If s is large enough, i.e. λ = 0, so that the minimum RSS value falls into the region of ridge regression parameter estimates then the alternative formulation yields the least square estimates.

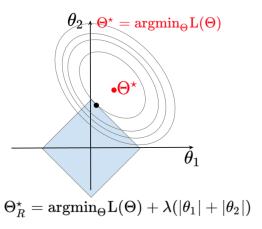


Lasso Alternative formulation

$$\Theta_R^{\star} = \operatorname*{argmin}_{\Theta} \sum_{i=1}^n (f(\mathbf{x}_i) - y_i)^2$$

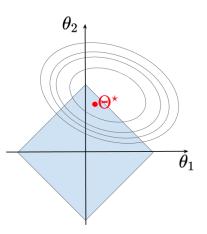
subject to $| heta_1| + \dots + | heta_m| \leq s$

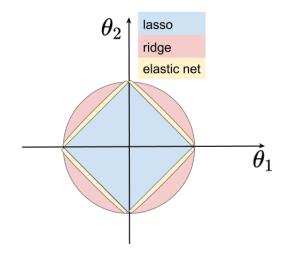
- the grey square represents the feasible region of the Lasso
- the contours represent different RSS values for the unregularized model



Lasso Alternative formulation

 If s is large enough, i.e. λ = 0, so that the minimum RSS value falls into the region of **loss** parameter estimates then the alternative formulation yields the primary solution.





$$f(\mathbf{x}) = rac{1}{1+e^{-\Theta^ op \mathbf{x}}}$$

$$L(\Theta) = -\sum_{i=1}^{n} y_i \log \mathsf{P}(y_i | \mathbf{x_i}; \Theta) + (1 - y_i) \log(1 - \mathsf{P}(y_i | \mathbf{x_i}; \Theta))$$

$$\Theta_{R}^{\star} = \operatorname{argmin}_{\Theta}[L(\Theta) + \lambda \cdot \mathsf{penalty}(\Theta)]$$

- Binary classifier using ROC curve (True Positive Rate vs. False Positive Rate)
- Model complexity, generalization error, Bias and variance
- Lasso and Ridge regularization for linear and logistic regression